

Network neutrality inference

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Katerina Argyraki*

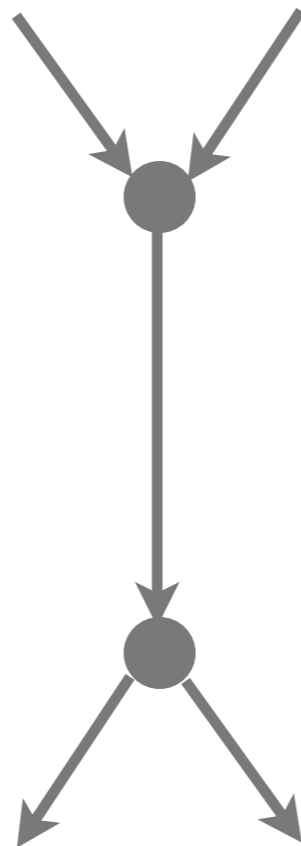
EPFL, UESTC

Neutrality

- ▶ Neutrality violation = a link subjects different flows to different policies

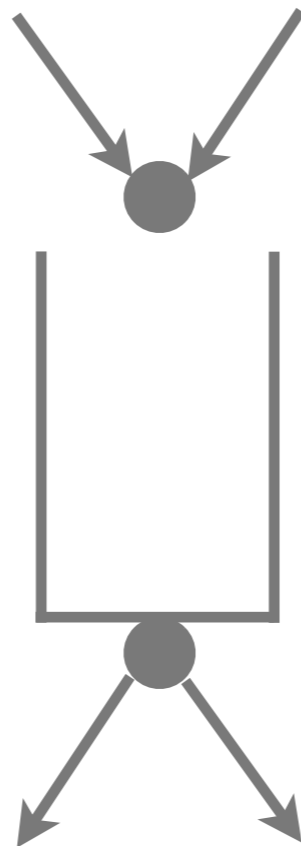
Neutrality

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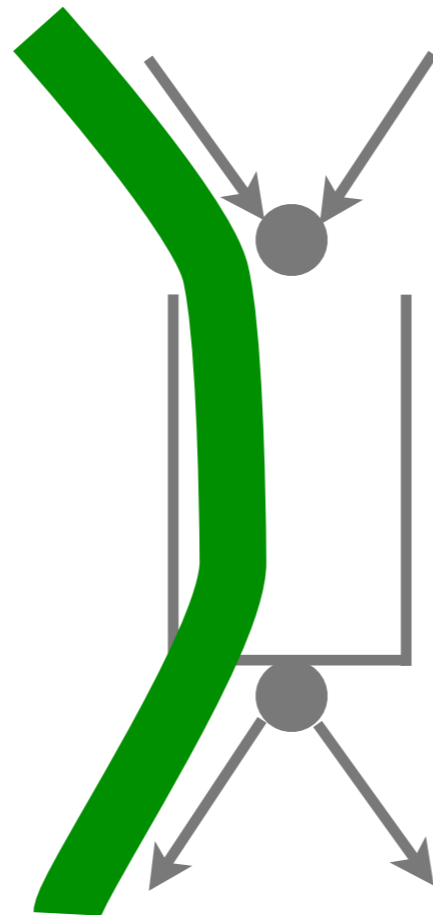
Neutrality

- ▶ Neutrality violation = a link subjects different flows to different policies



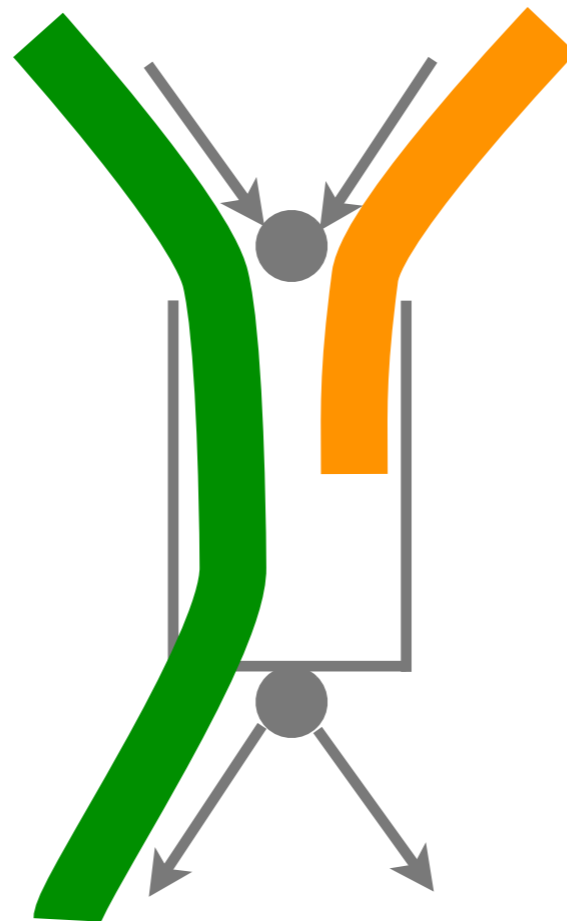
Neutrality

- ▶ Neutrality violation = a link subjects different flows to different policies



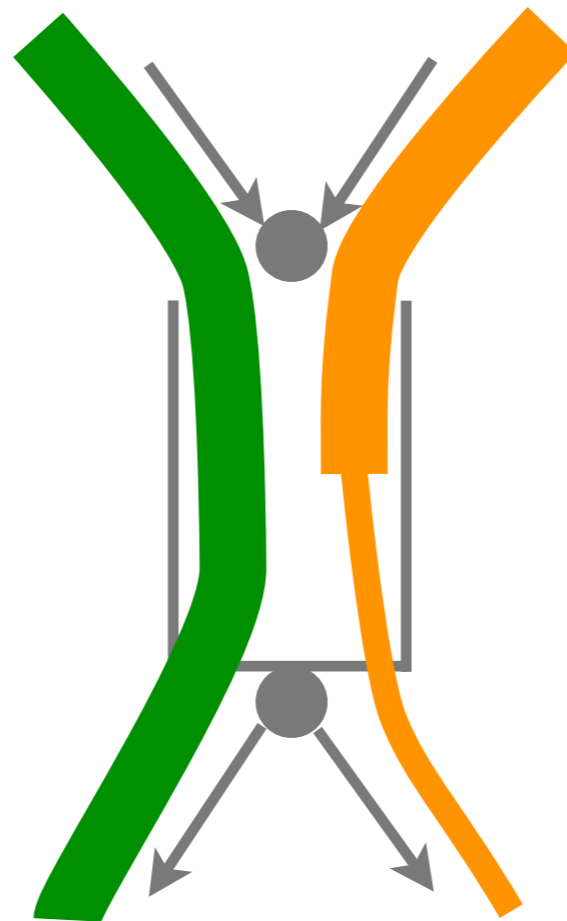
Neutrality

- ▶ Neutrality violation = a link subjects different flows to different policies



Neutrality

- ▶ Neutrality violation = a link subjects different flows to different policies



Transparency

- ▶ Neutrality violation should be transparent
- ▶ Is it feasible to externally observe neutrality violations?
- ▶ Is it feasible to localize them to specific links?

Inconsistent observations

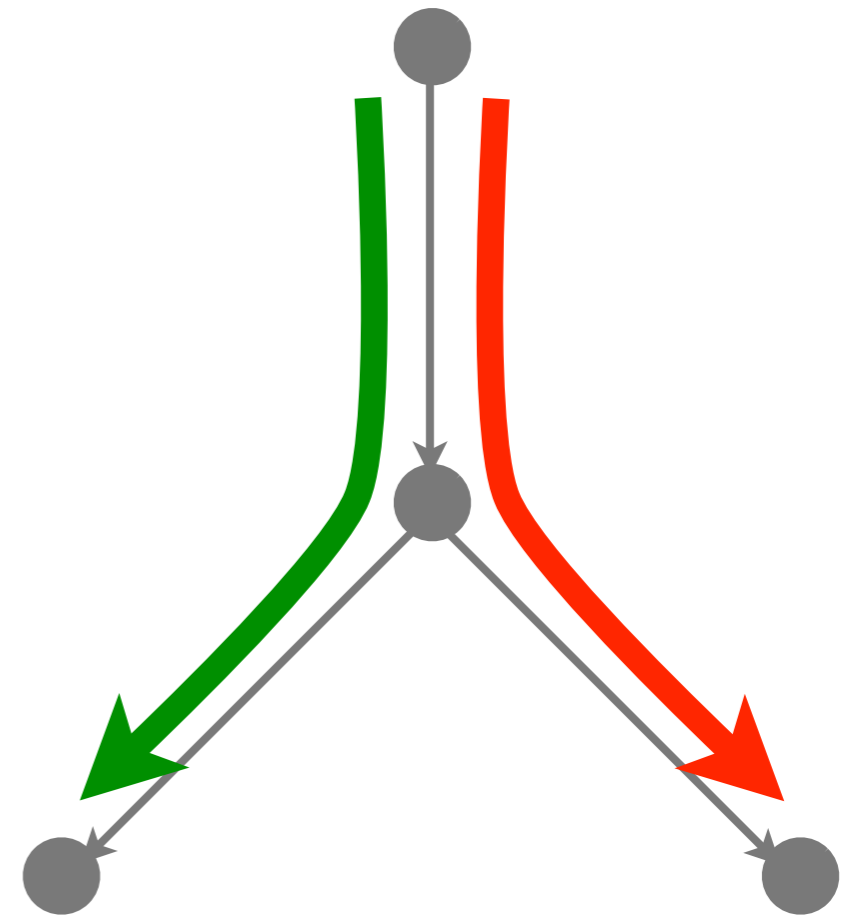
- ▶ When the network is non-neutral, if we make diverse external observations, these will be inconsistent with each other.

Network tomography

- ▶ Input: network topology,
path measurements
- ▶ Output: link properties
 - *average loss rate*
 - *average latency*
 - *congestion status*
 - *congestion probability*

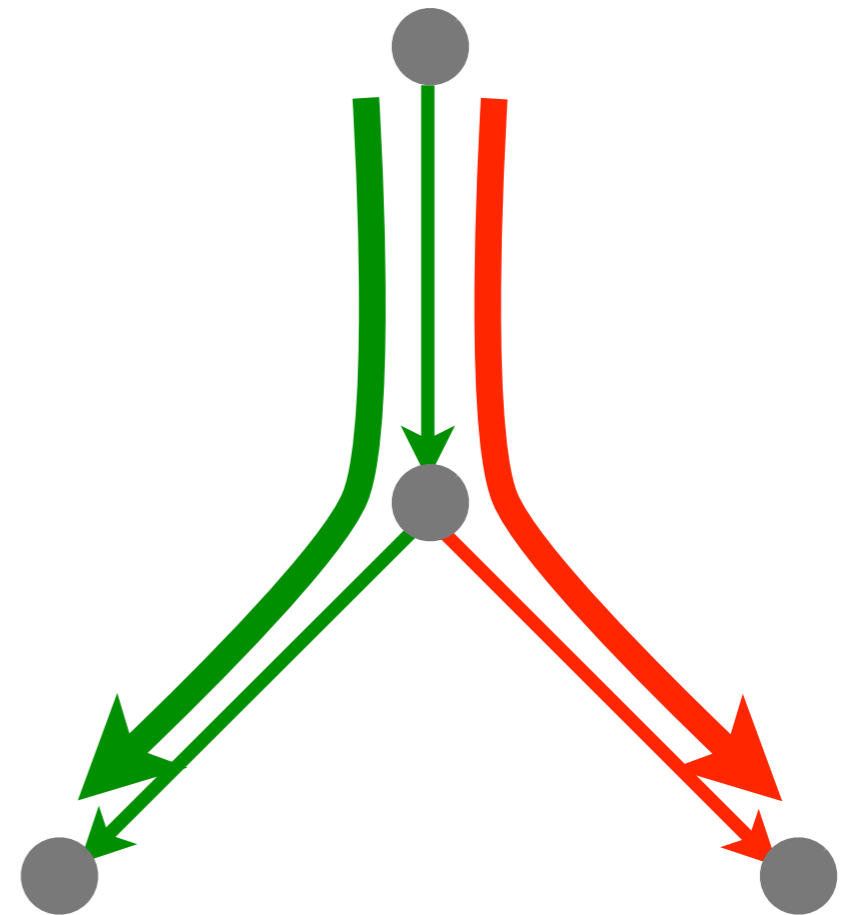
Network tomography

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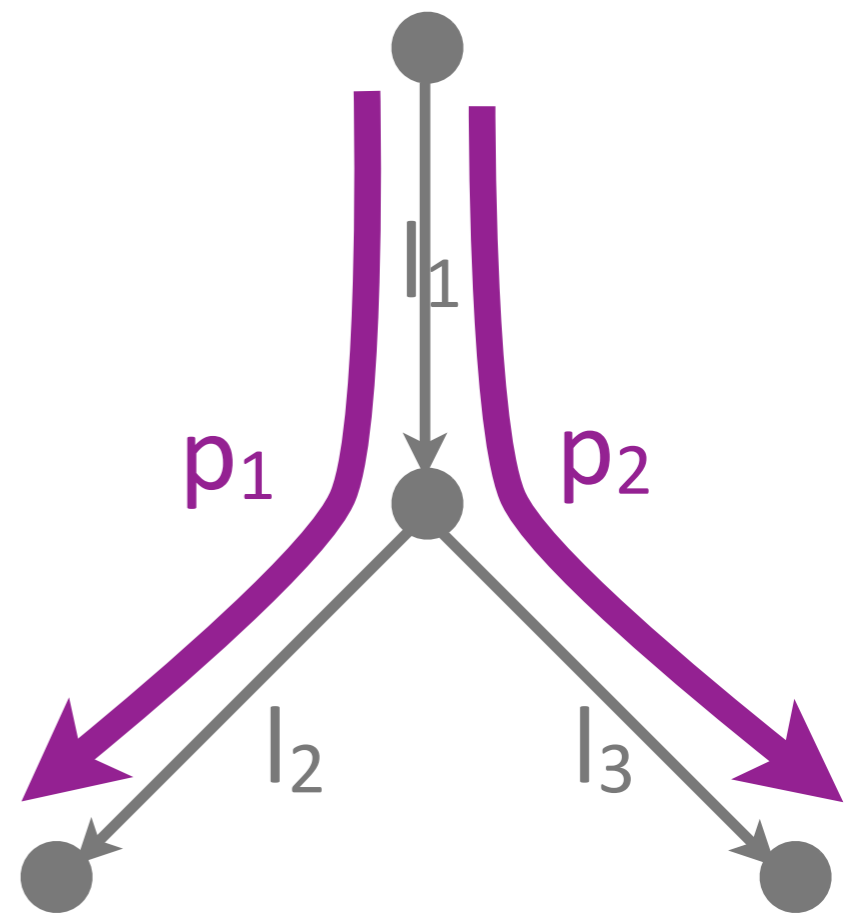


Network tomography

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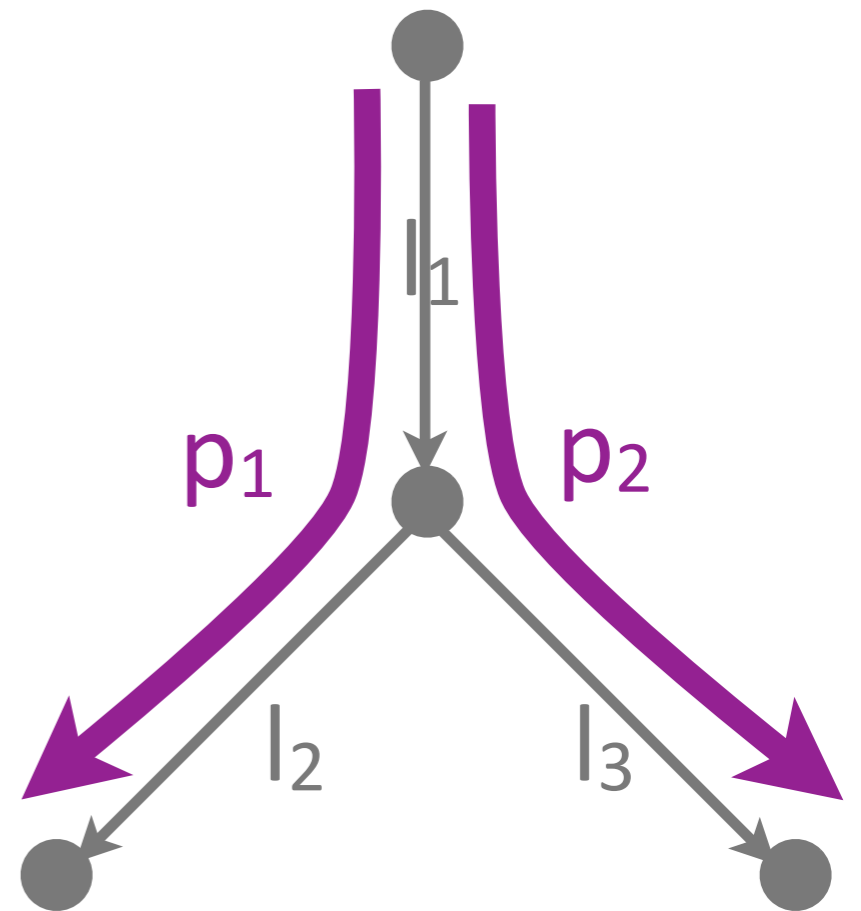


Network tomography



Network tomography

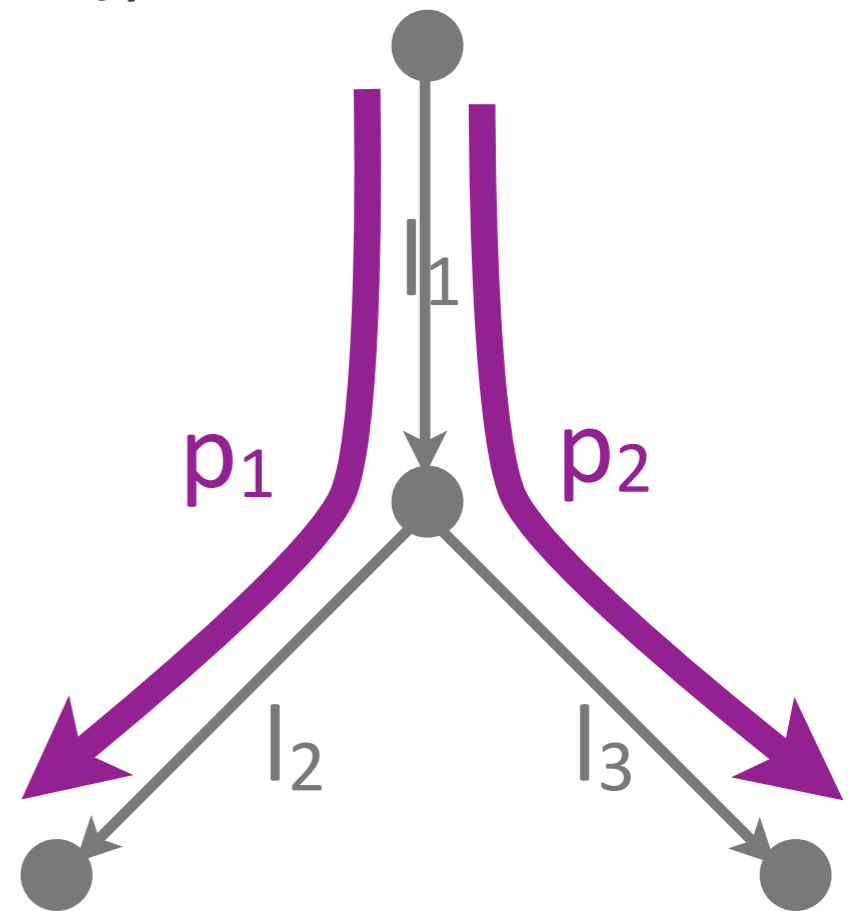
$$P\{p_1 \text{ good}\} = P\{l_1 \text{ good}\} * P\{l_2 \text{ good}\}$$



Network tomography

$$P\{p_1 \text{ good}\} = P\{l_1 \text{ good}\} * P\{l_2 \text{ good}\}$$

$$\log(P\{p_1 \text{ good}\}) = \log(P\{l_1 \text{ good}\}) + \log(P\{l_2 \text{ good}\})$$

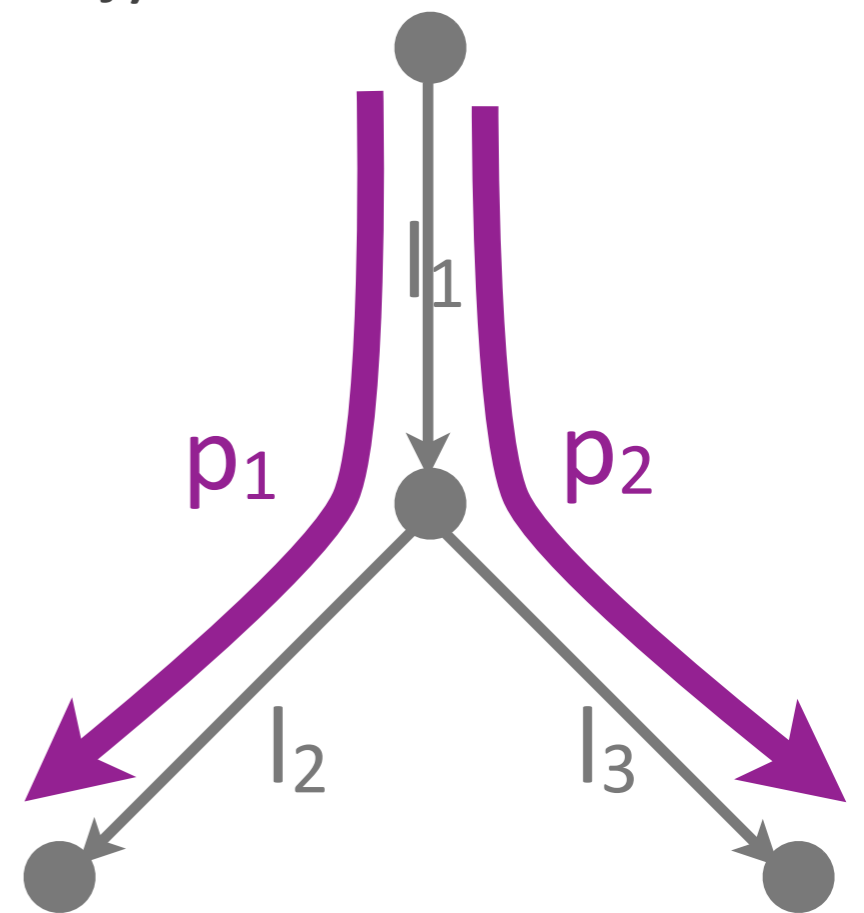


Network tomography

$$P\{p_1 \text{ good}\} = P\{l_1 \text{ good}\} * P\{l_2 \text{ good}\}$$

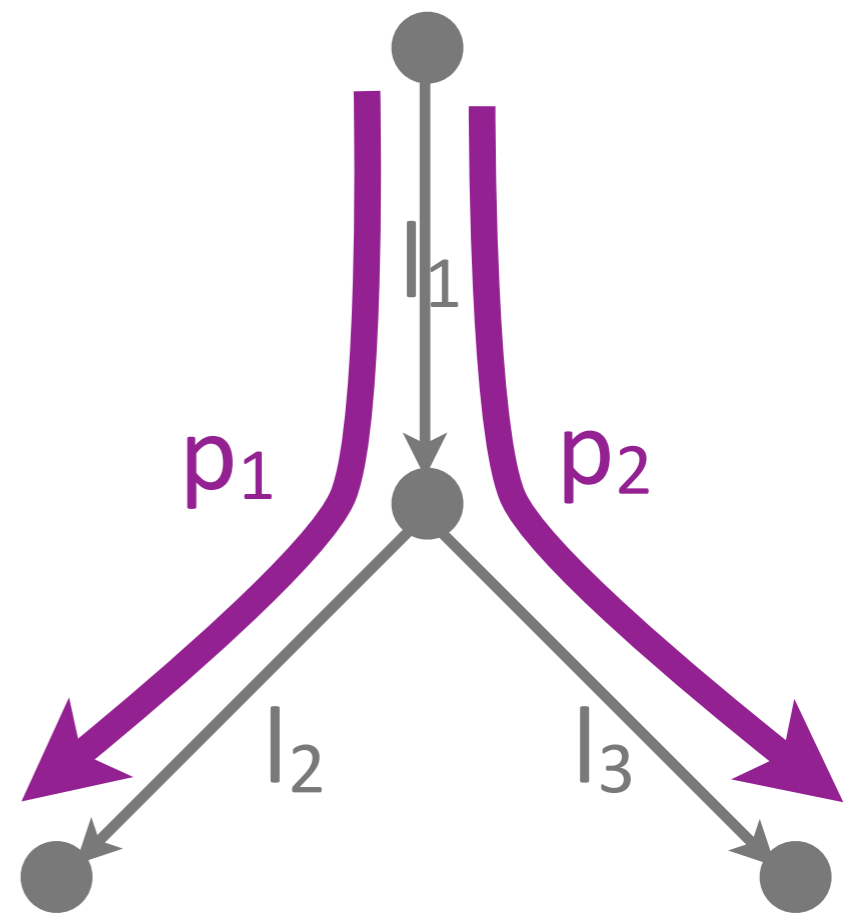
$$\log(P\{p_1 \text{ good}\}) = \log(P\{l_1 \text{ good}\}) + \log(P\{l_2 \text{ good}\})$$

$$Y_1 = X_1 + X_2$$



Network tomography

$$Y_1 = X_1 + X_2$$

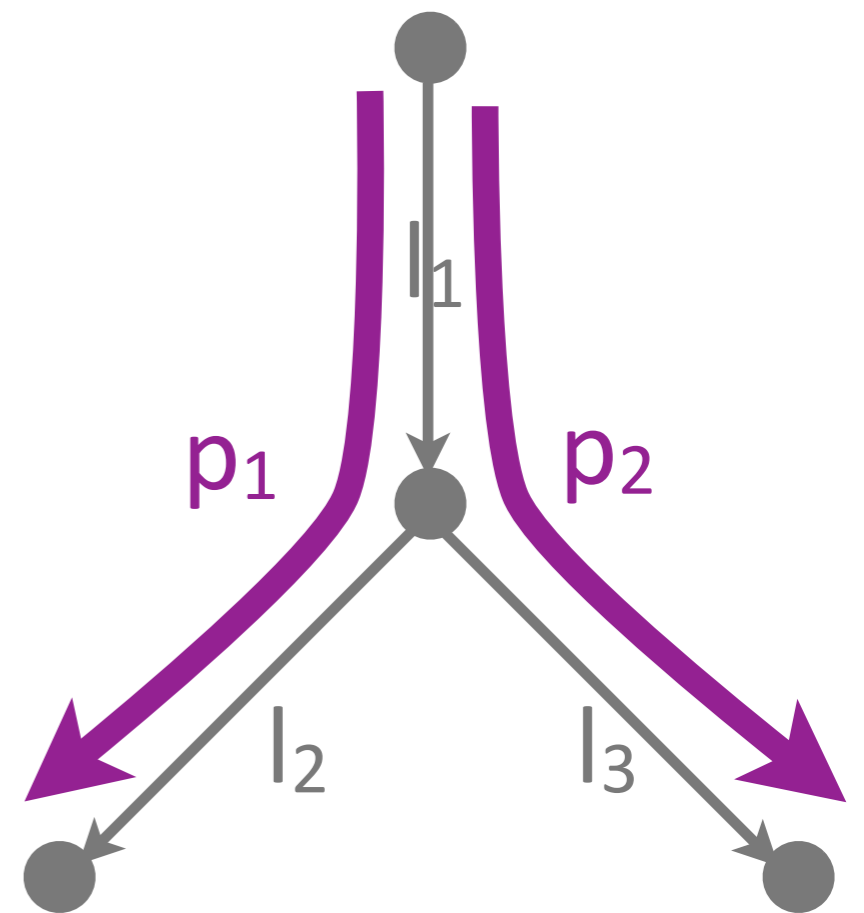


Network tomography

link properties (unknowns)

$$\begin{aligned} Y_1 &= X_1 + X_2 \\ Y_2 &= X_1 + X_3 \\ Y_{12} &= X_1 + X_2 + X_3 \end{aligned}$$

↑
e2e path measurements



Tomography and neutrality

- ▶ Tomography fundamentally assumes network neutrality
- ▶ A link has the same property for all paths that traverse that link

Neutrality and tomography

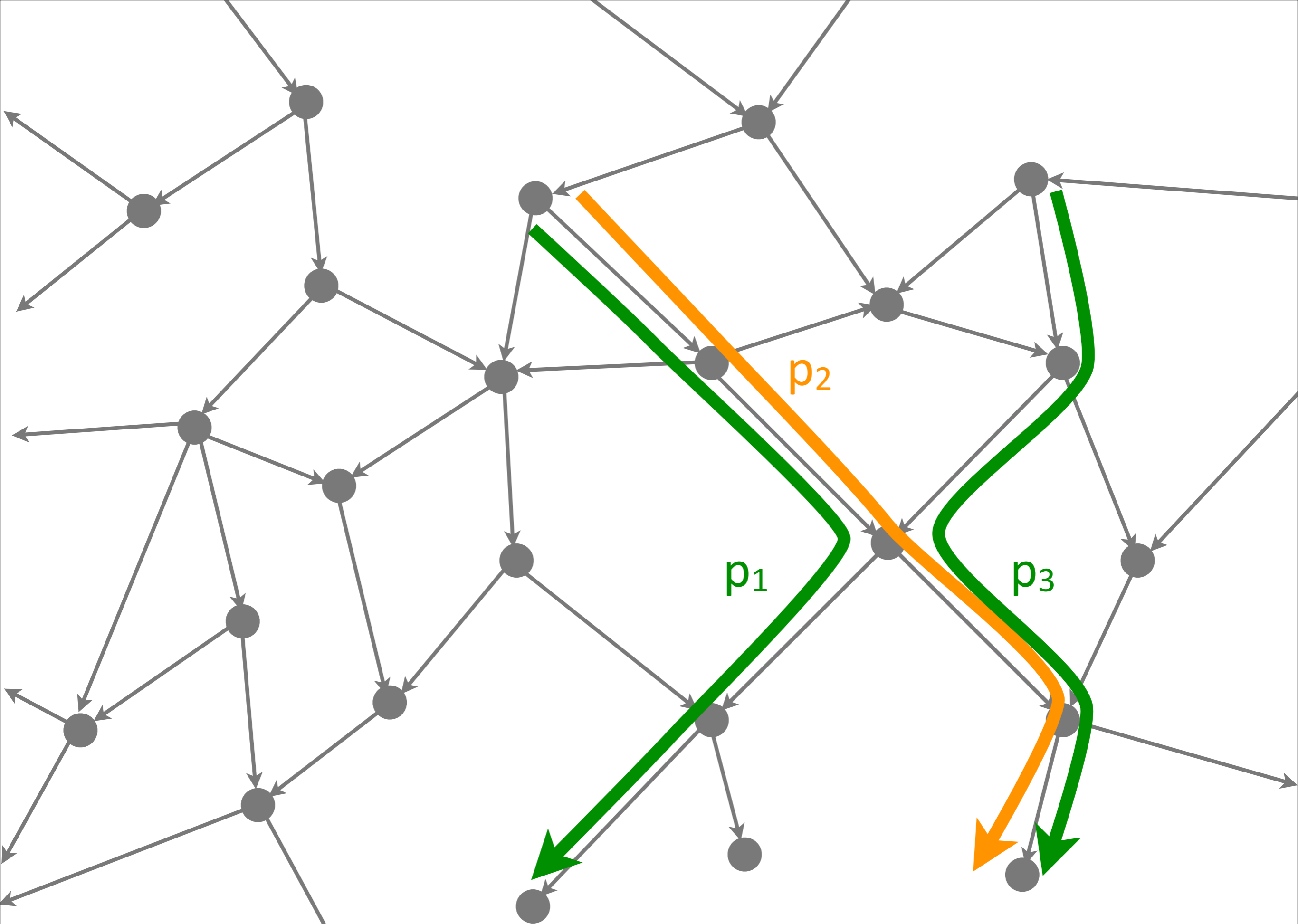
- ▶ In a neutral network, any tomographic system of equations has a solution
- ▶ If we find an unsolvable system, this indicates neutrality violation

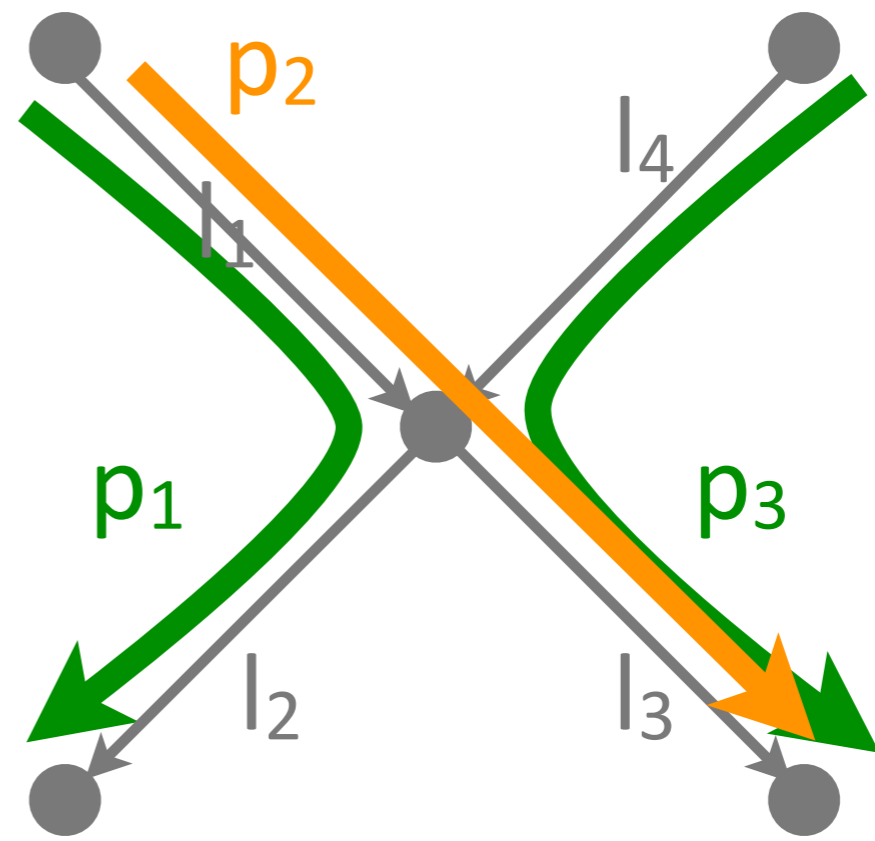
Outline

- ▶ Observability of neutrality violations
- ▶ Localization of neutrality violations
- ▶ Algorithm + results

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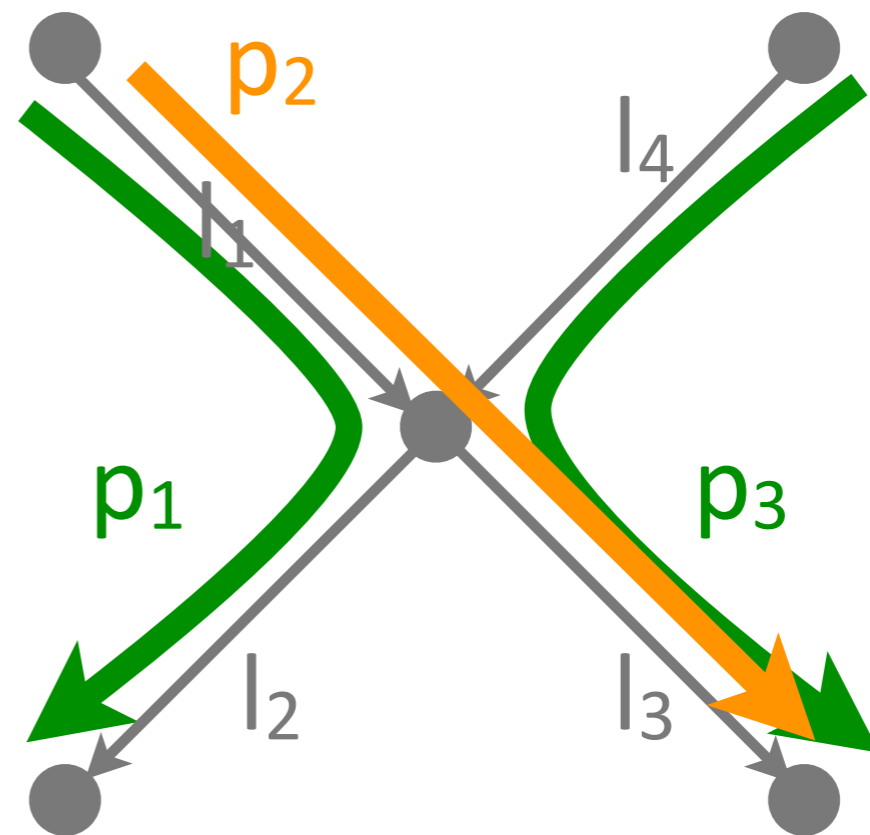




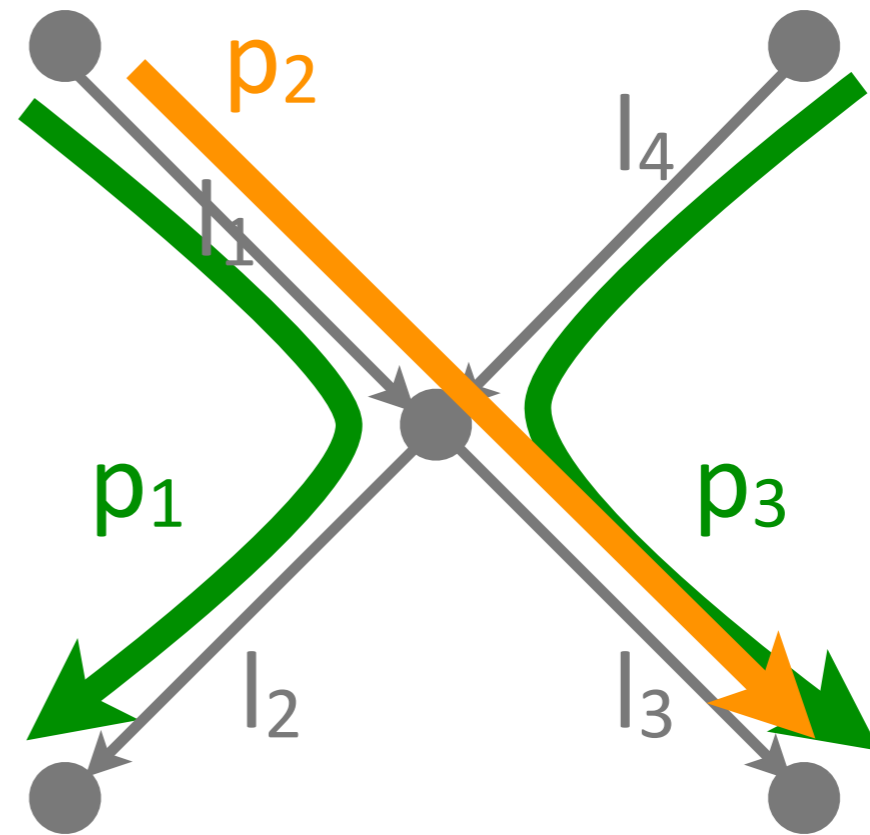
$$Y_1 = X_1 + X_2$$

$$Y_2 = X_1 + X_3$$

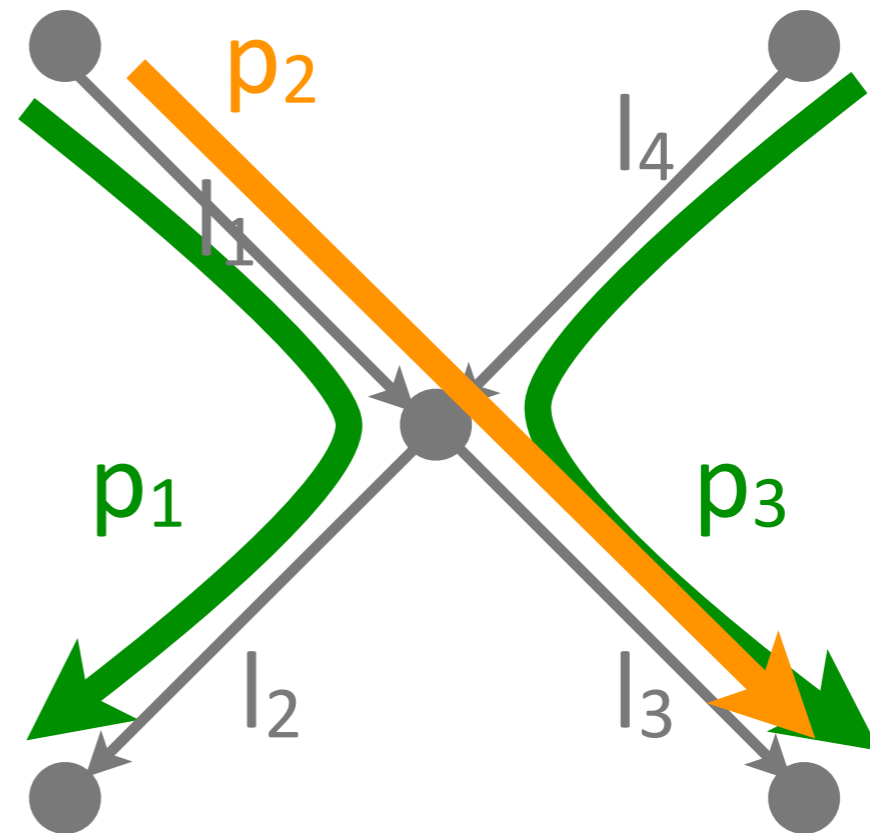
$$Y_3 = X_3 + X_4$$



$$\begin{aligned} 0 &= X_1 + X_2 \\ 0 > Y_2 &= X_1 + X_3 \\ 0 &= X_3 + X_4 \end{aligned}$$

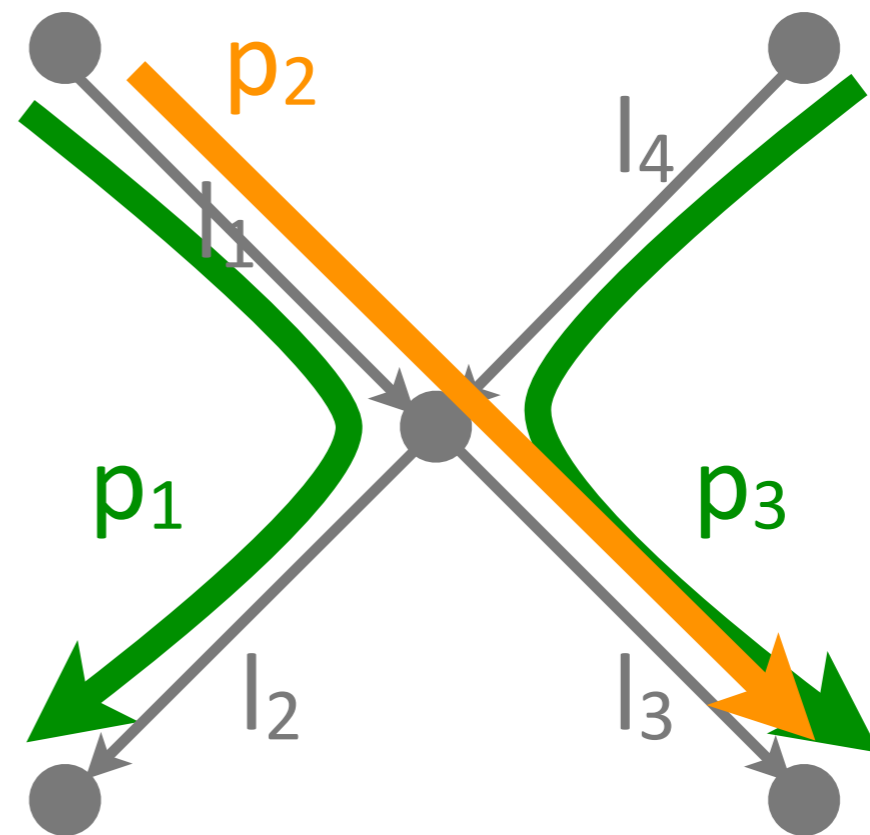


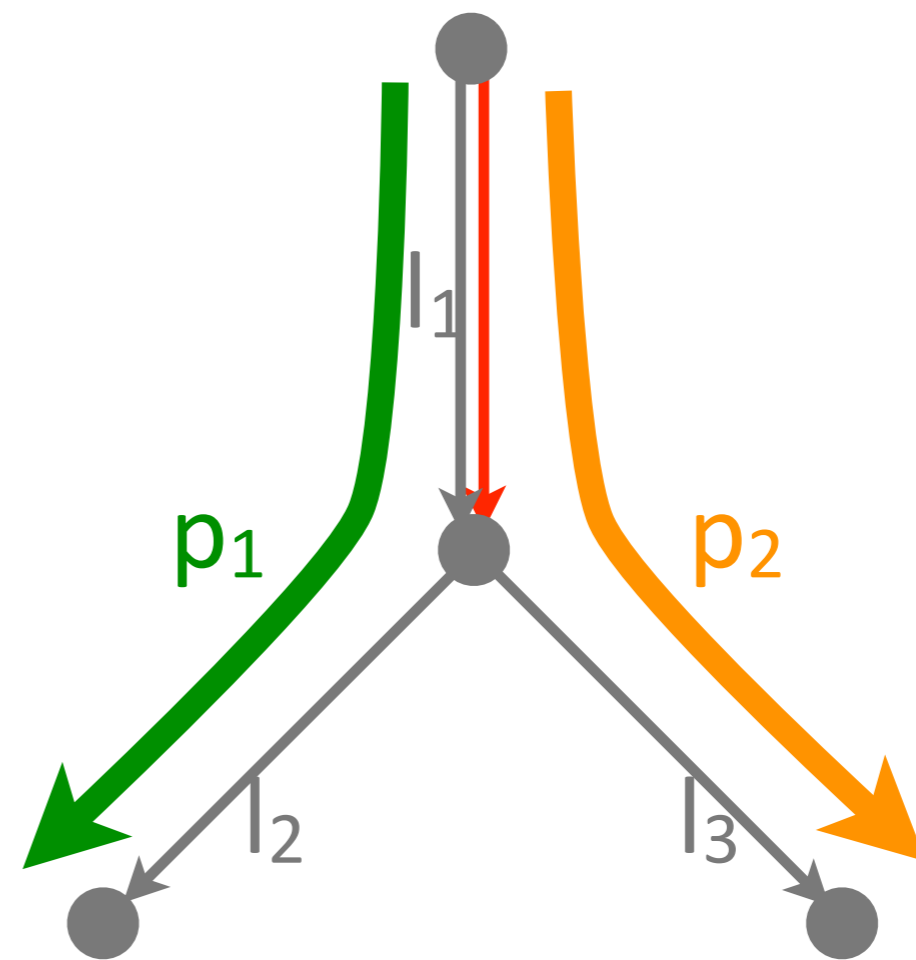
$$\begin{aligned}
 0 &= \cancel{X_1}^0 + \cancel{X_2}^0 \\
 0 > Y_2 &= \cancel{X_1}^0 + \cancel{X_3}^0 \\
 0 &= \cancel{X_3}^0 + \cancel{X_4}^0
 \end{aligned}$$



Observable neutrality violation

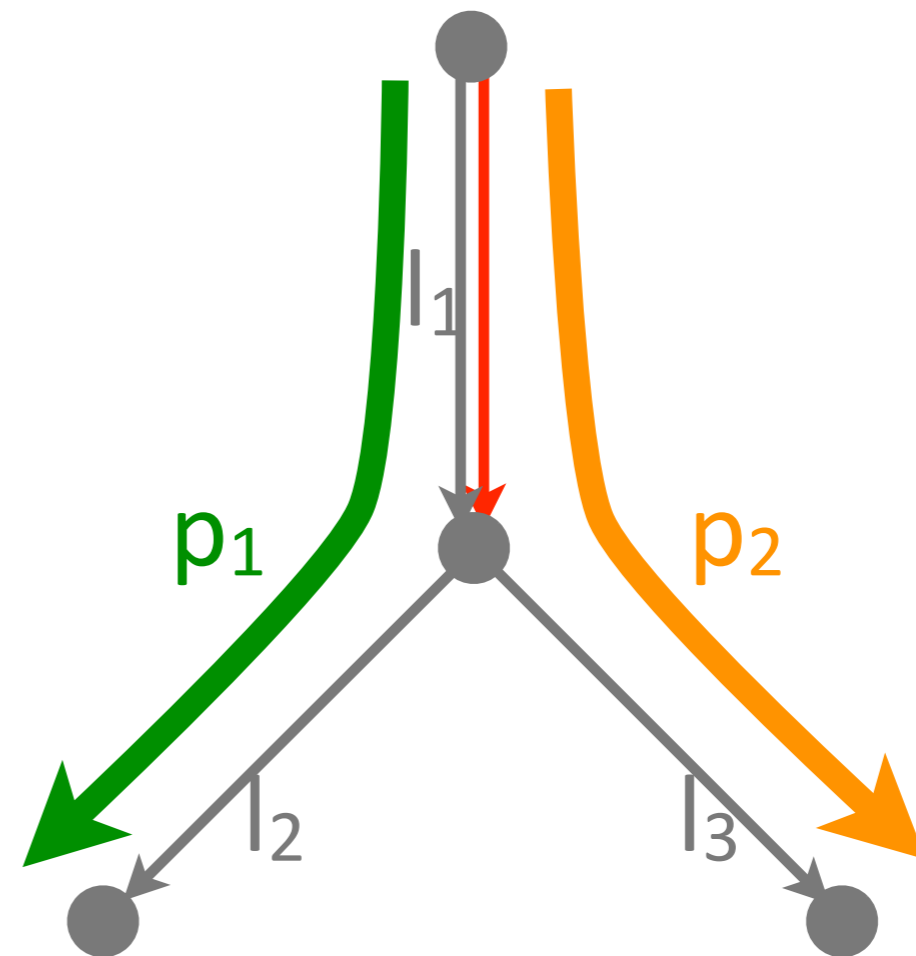
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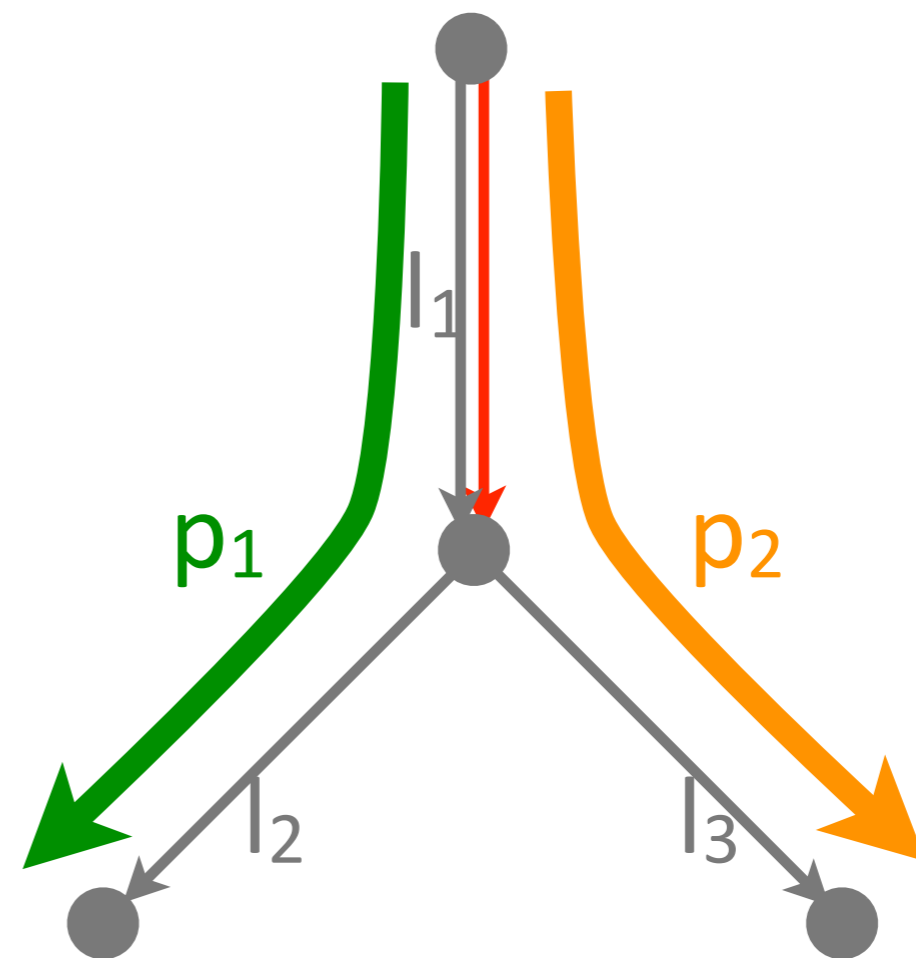


$$Y_1 = X_1 + X_2$$

$$Y_2 = X_1 + X_3$$

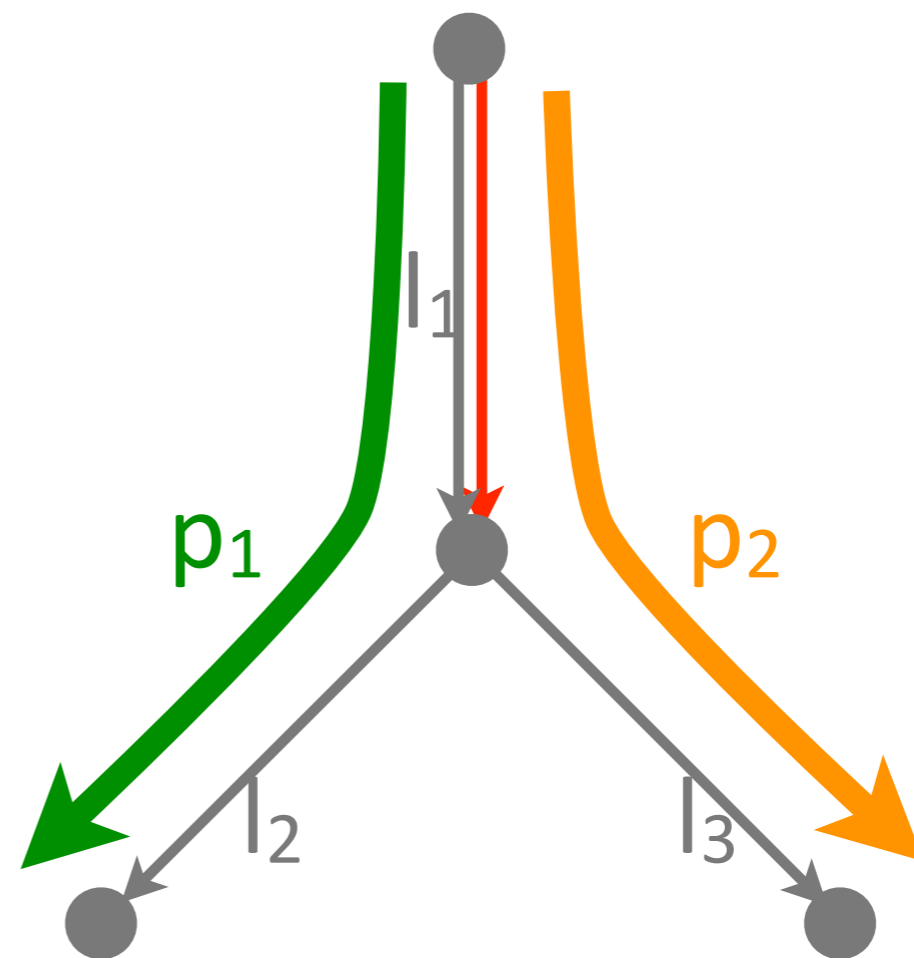


$$0 = X_1 + X_2$$
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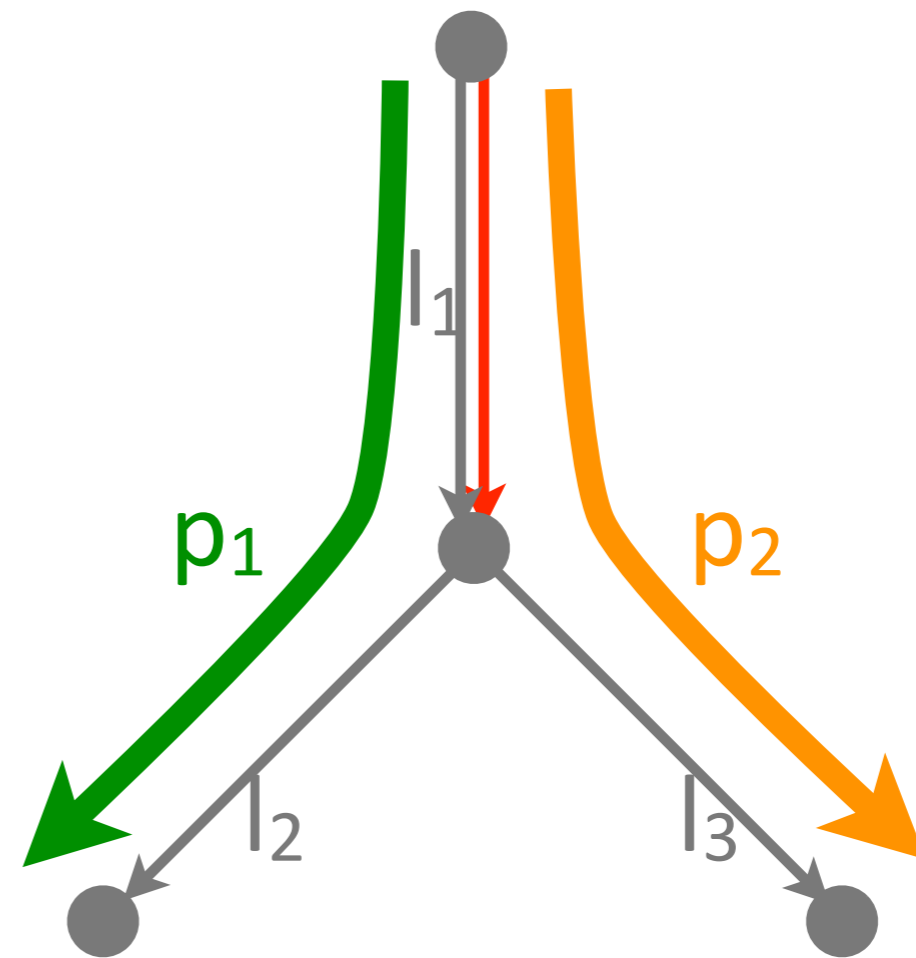
$$0 = \cancel{X_1}^0 + \cancel{X_2}^0$$

$$0 > Y_2 = \cancel{X_1}^0 + X_3$$



Non-observable neutrality violation

$$0 = \cancel{X_1}^0 + \cancel{X_2}^0$$
$$0 > Y_2 = \cancel{X_1}^0 + X_3$$



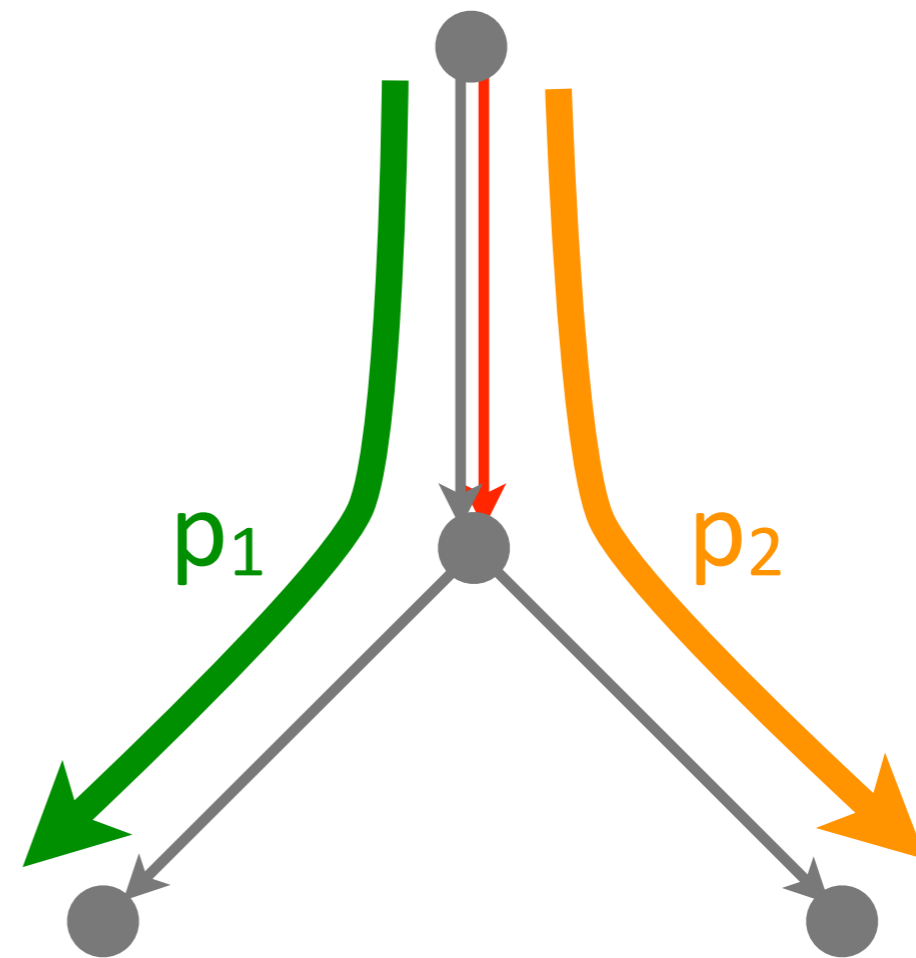
Equivalent neutral network

- ▶ Any non-neutral network has a neutral equivalent
- ▶ A neutral network that:
*given the same traffic input
would produce the same external observations
as the non-neutral network.*

Equivalent neutral network

- ▶ A purely theoretical construct
- ▶ Enables to formally specify which neutrality violations are externally observable

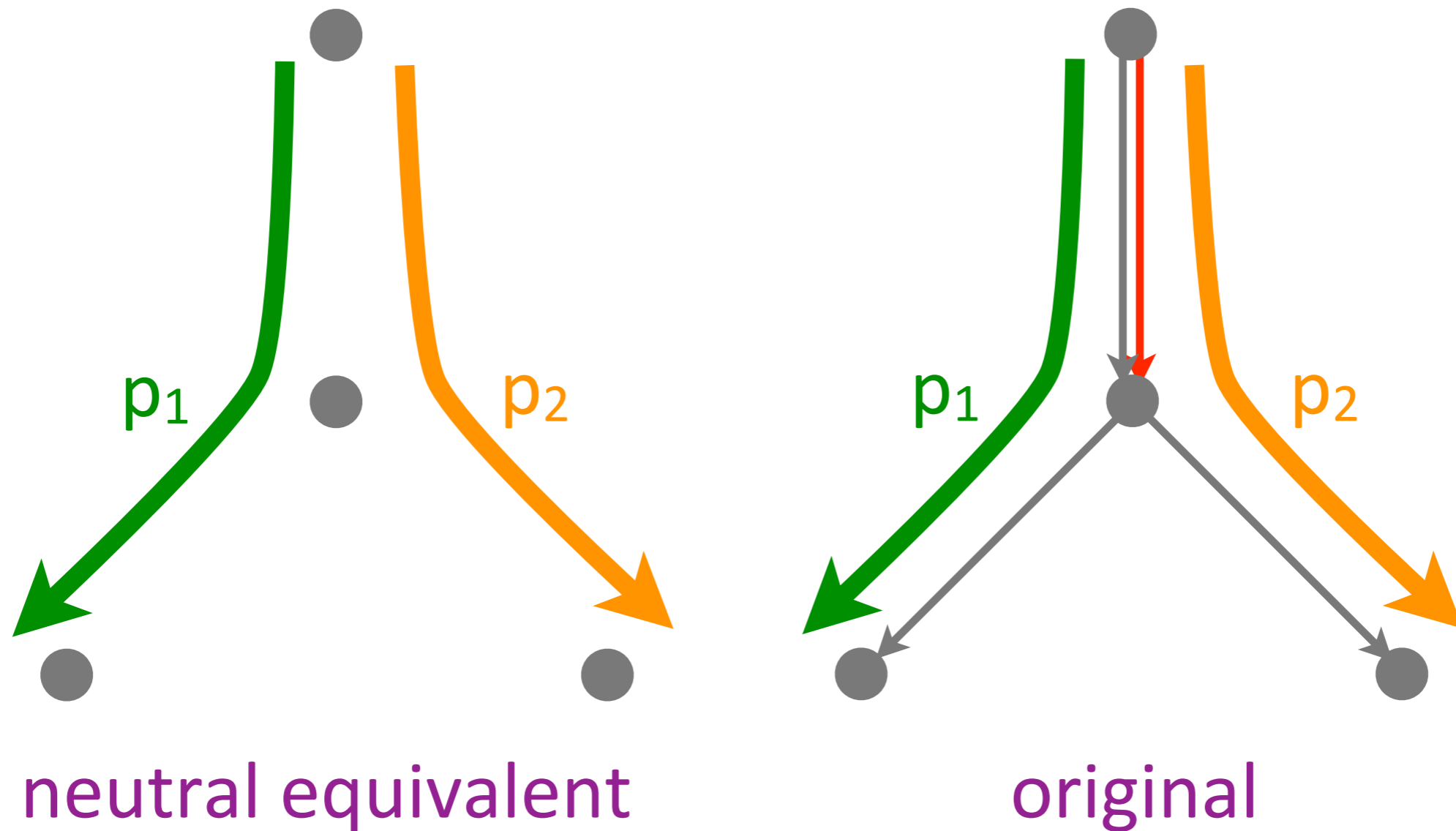
Non-observable neutrality violation



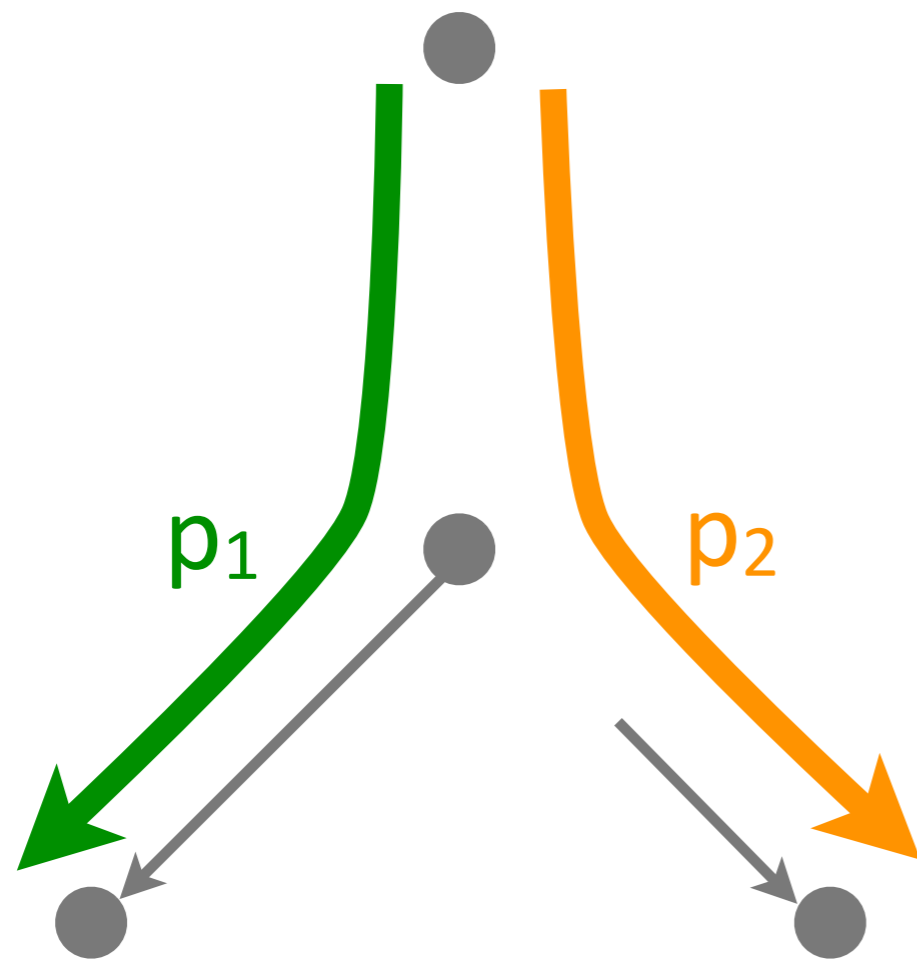
neutral equivalent

original

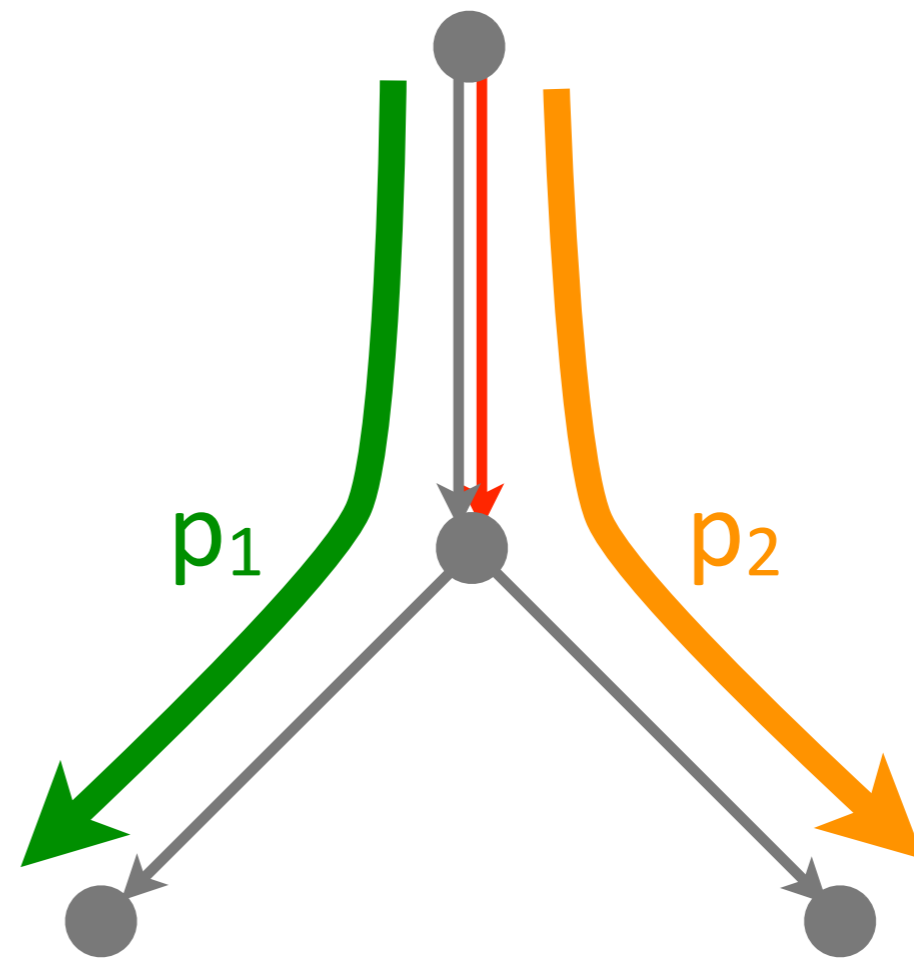
Non-observable neutrality violation



Non-observable neutrality violation

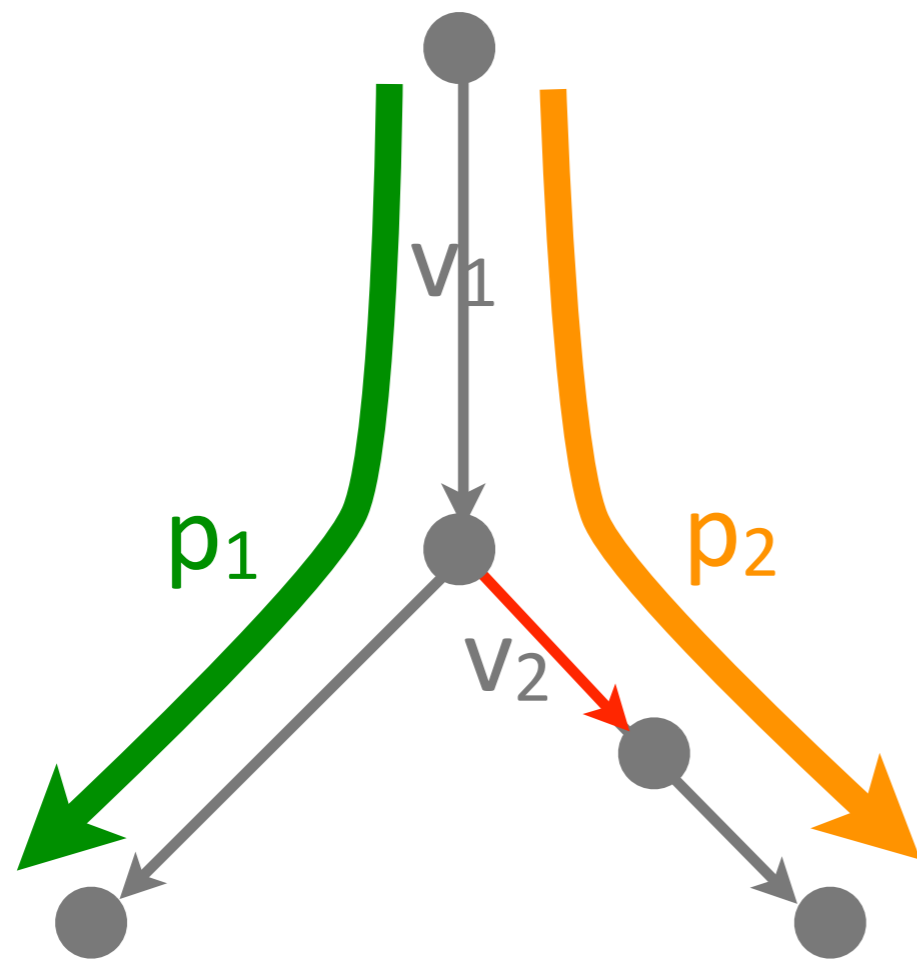


neutral equivalent

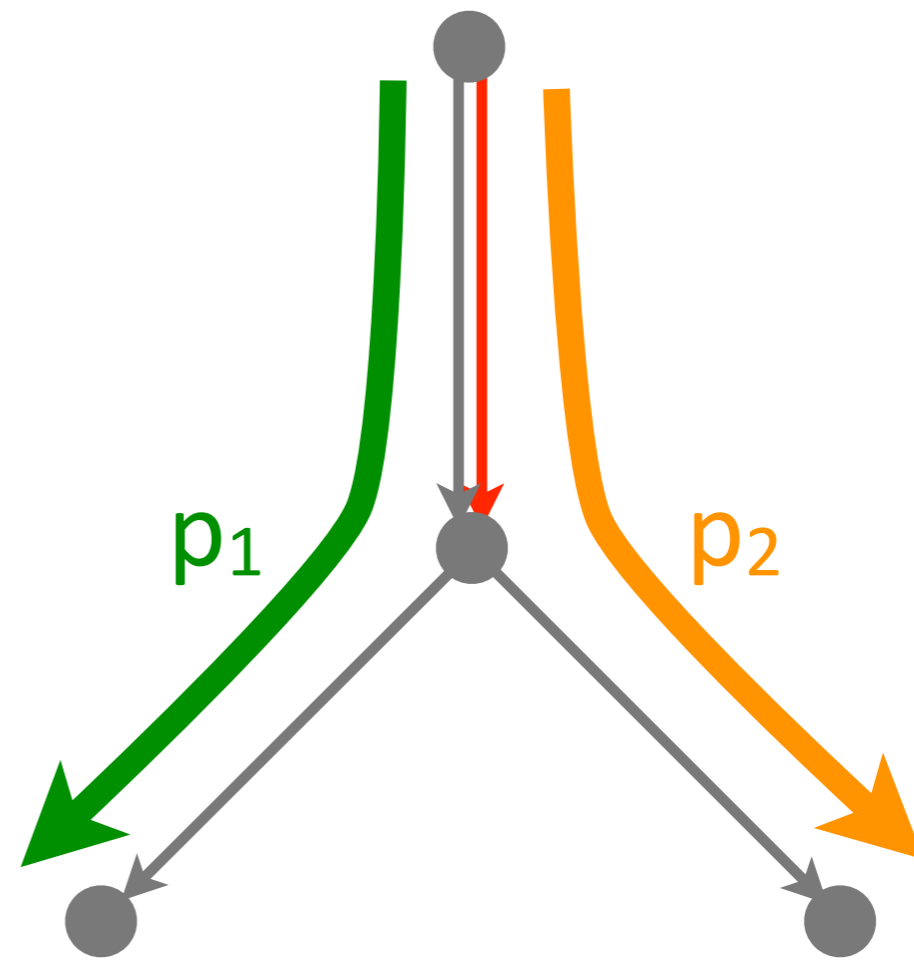


original

Non-observable neutrality violation

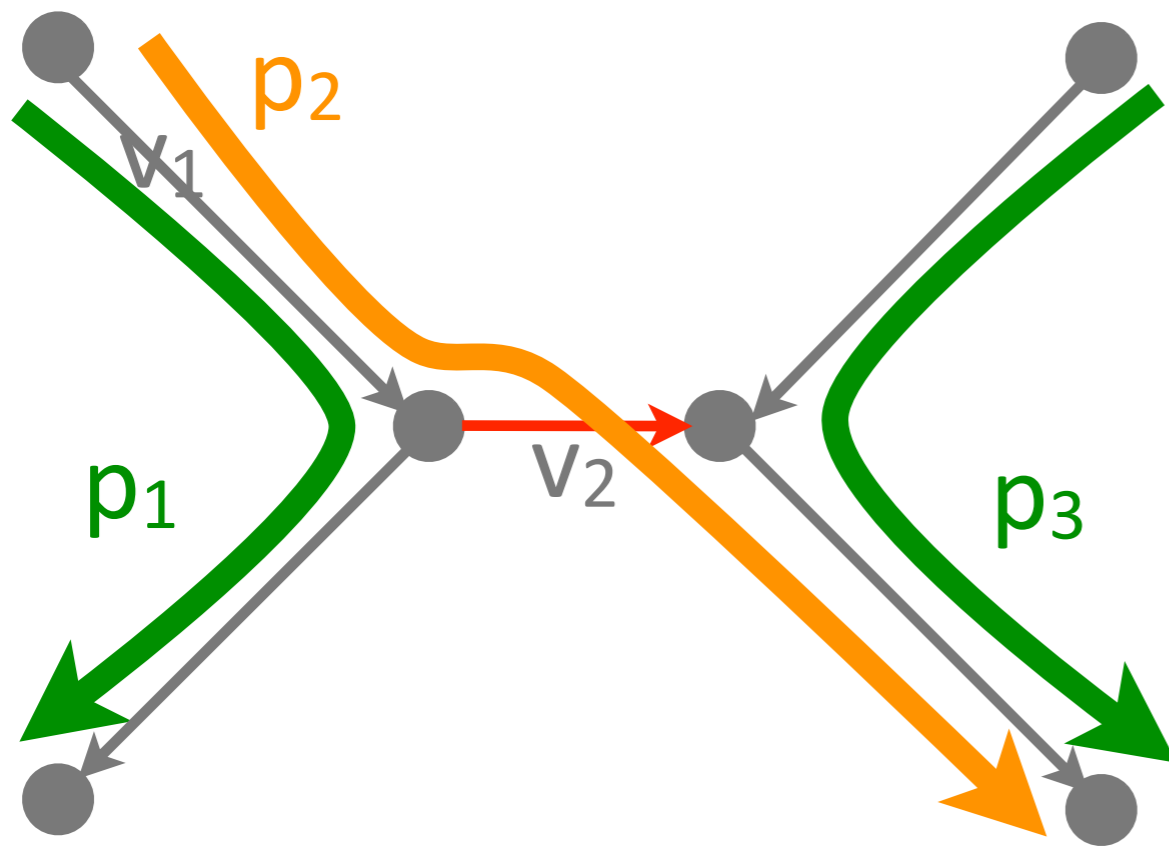


neutral equivalent

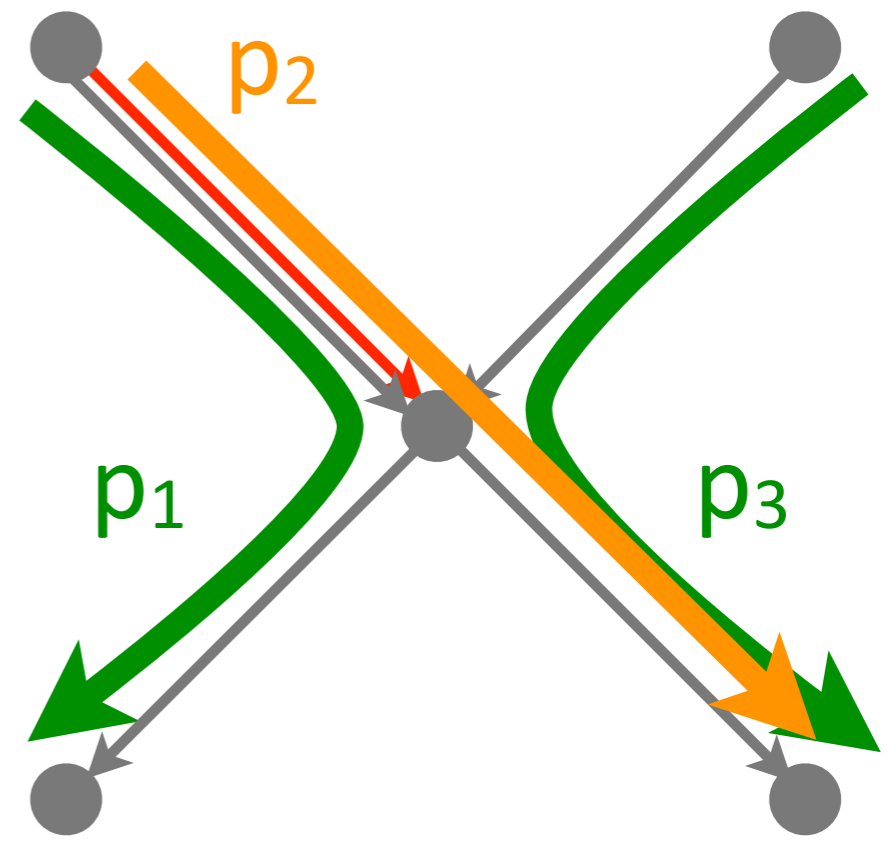


original

Observable neutrality violation



neutral equivalent



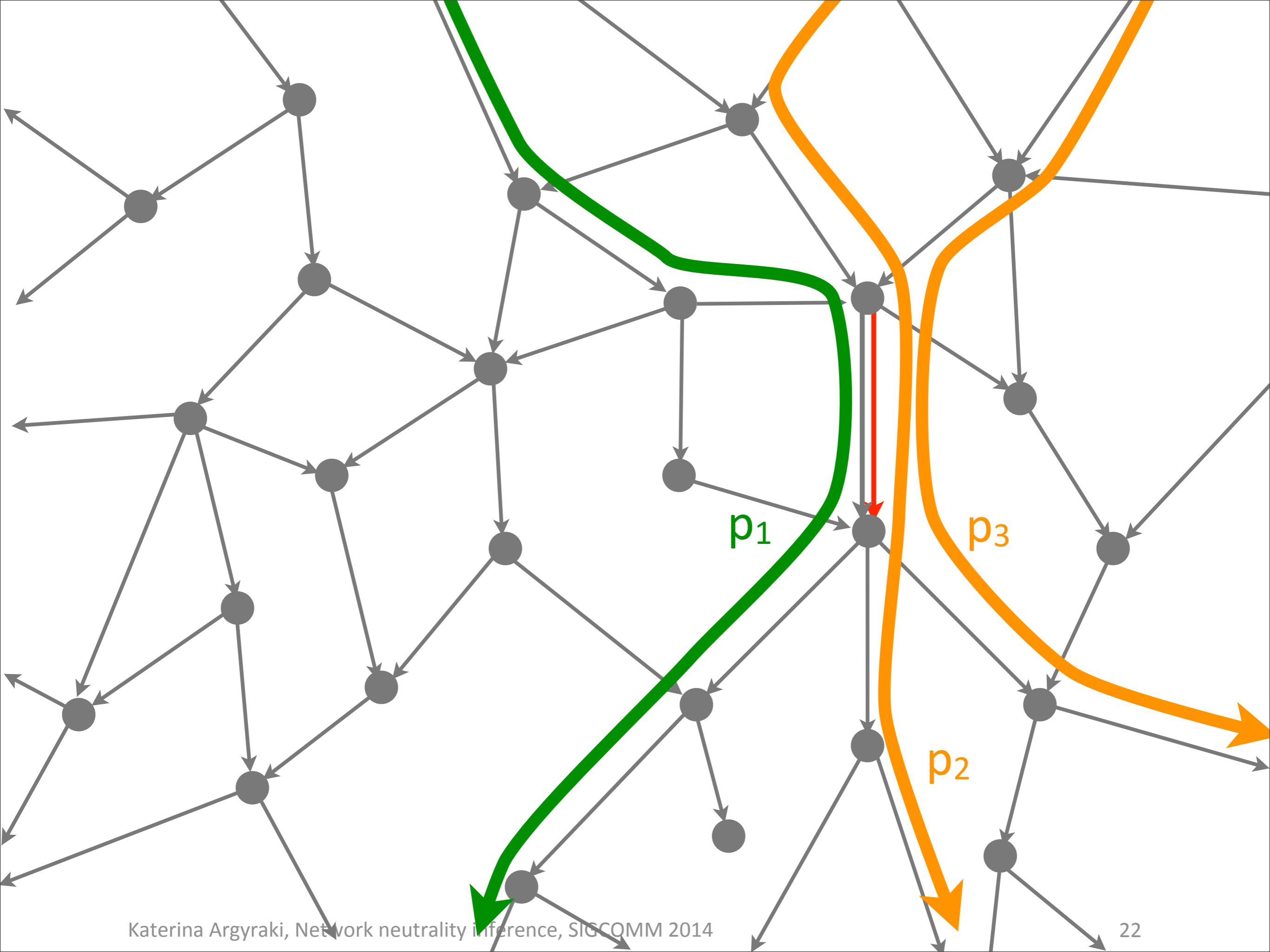
original

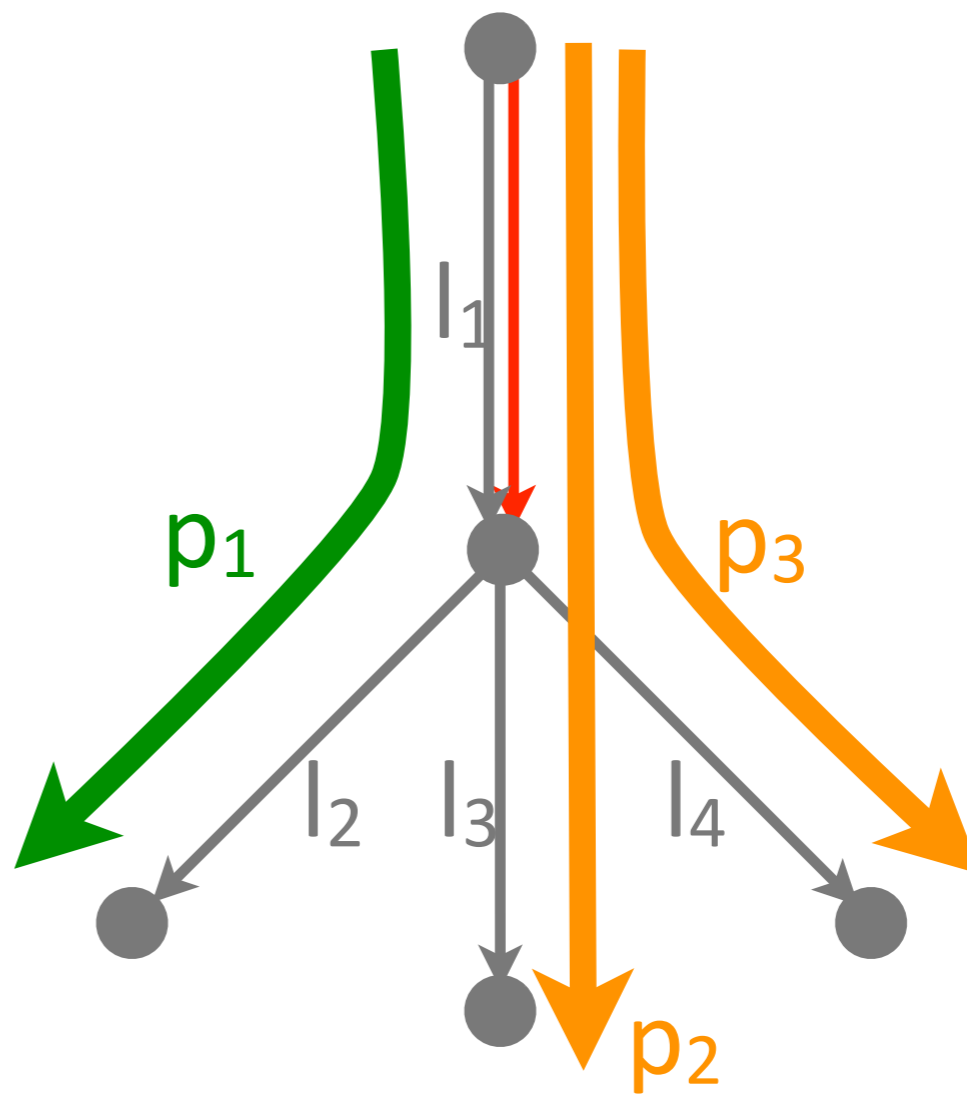
Observability

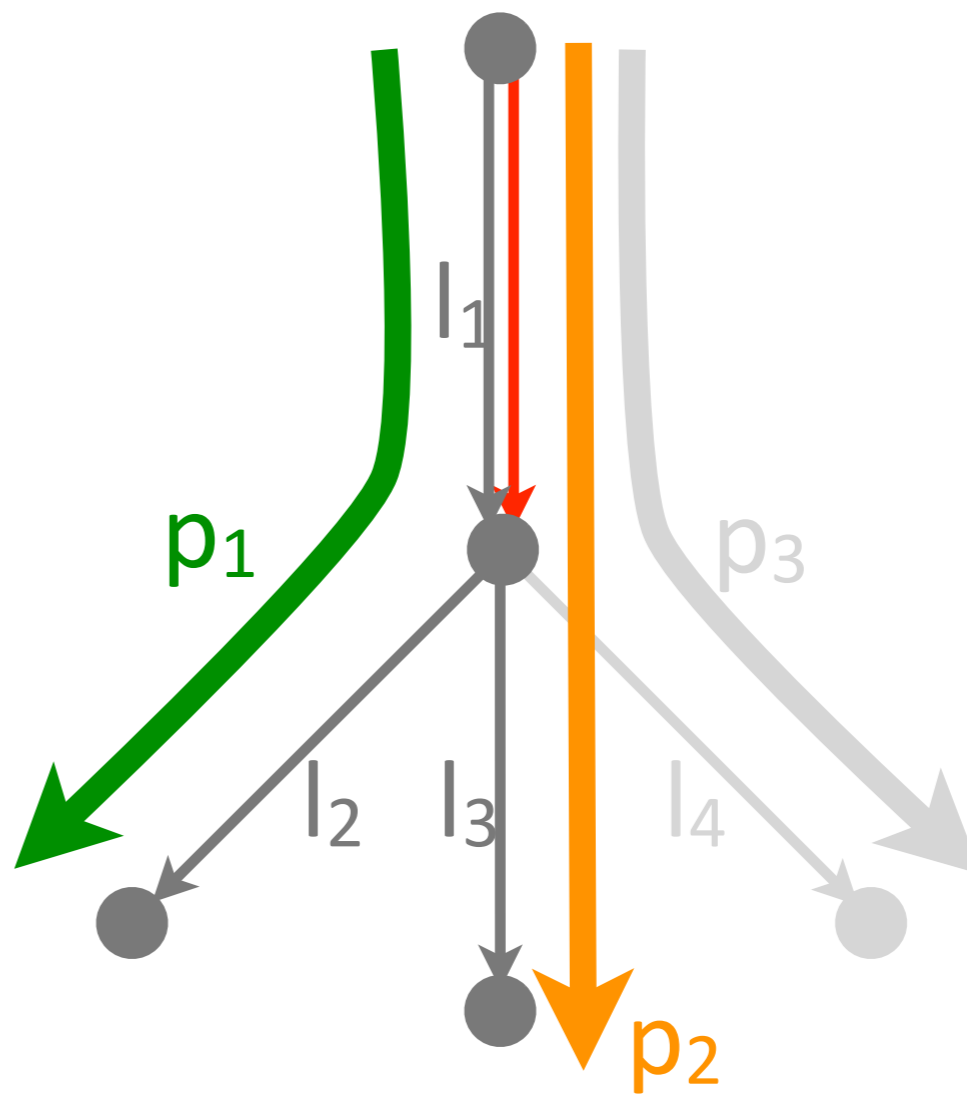
- ▶ Neutrality violation is **externally observable**,
if and only if
there exists at least one
distinguishable virtual link
in the equivalent neutral network.

Outline

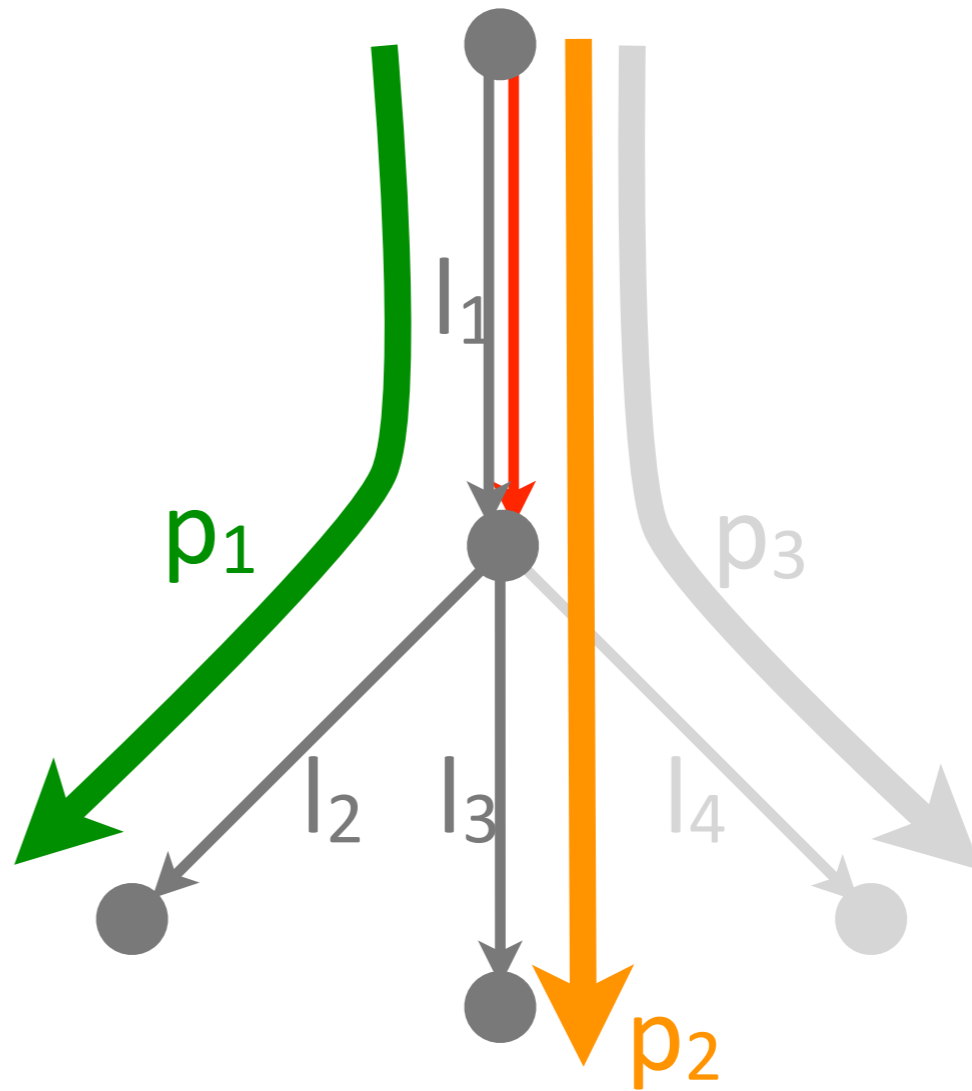
- ▶ Observability of neutrality violation
- ▶ **Localization of neutrality violations**
- ▶ Algorithm + results





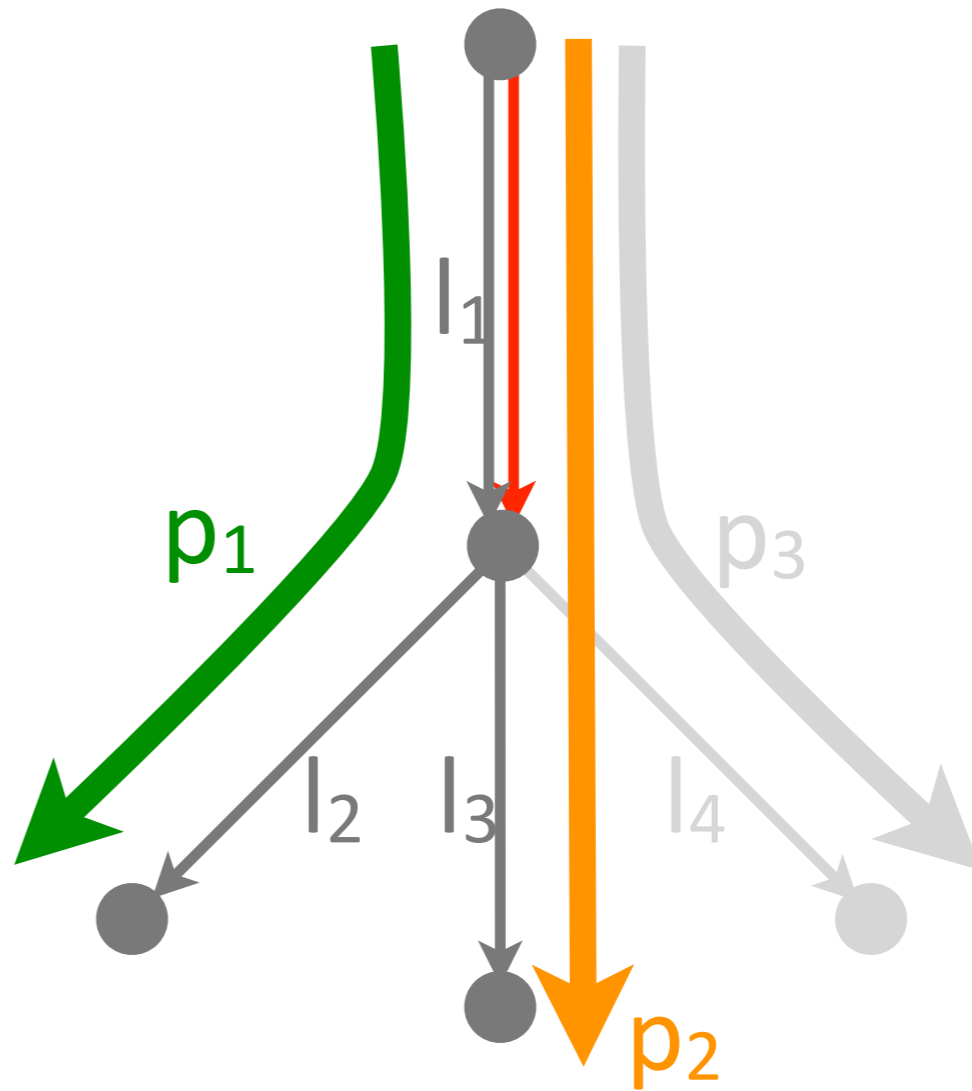


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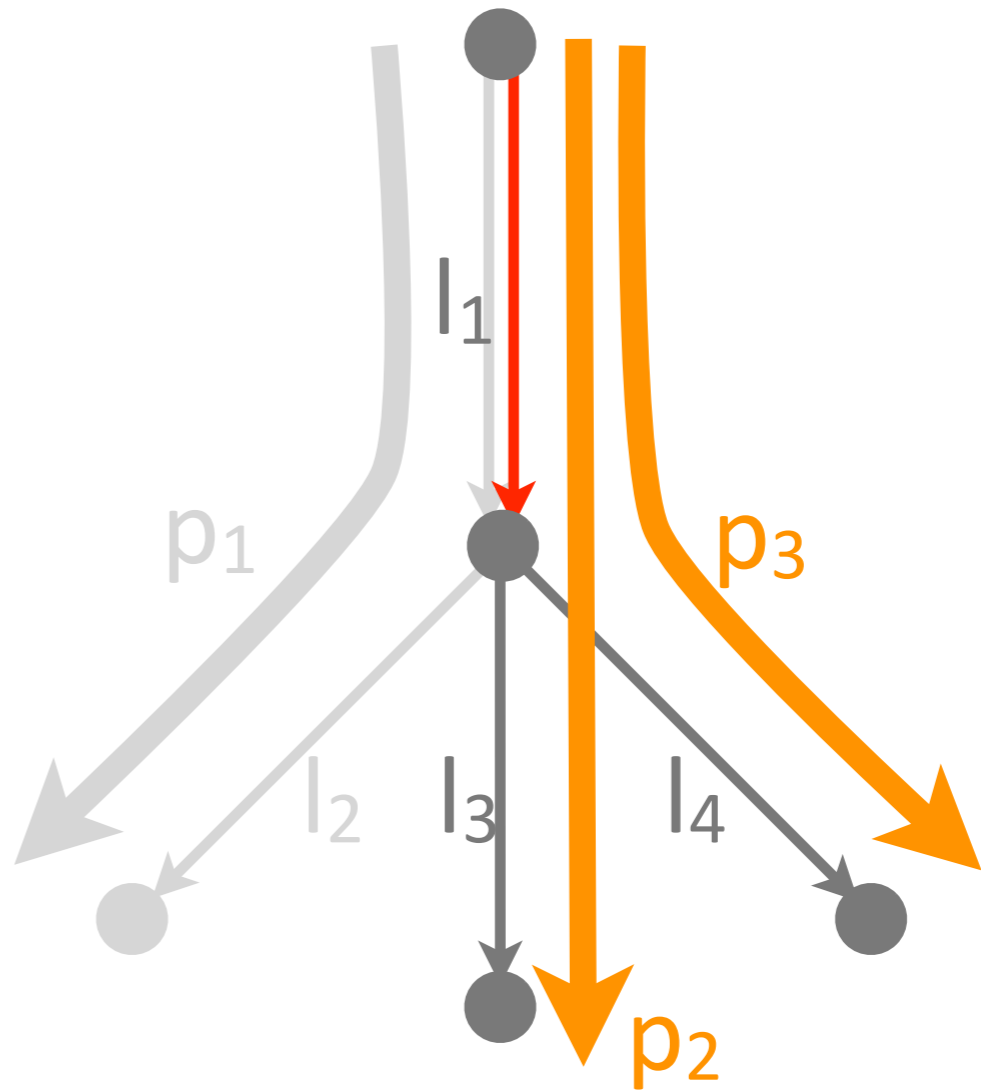
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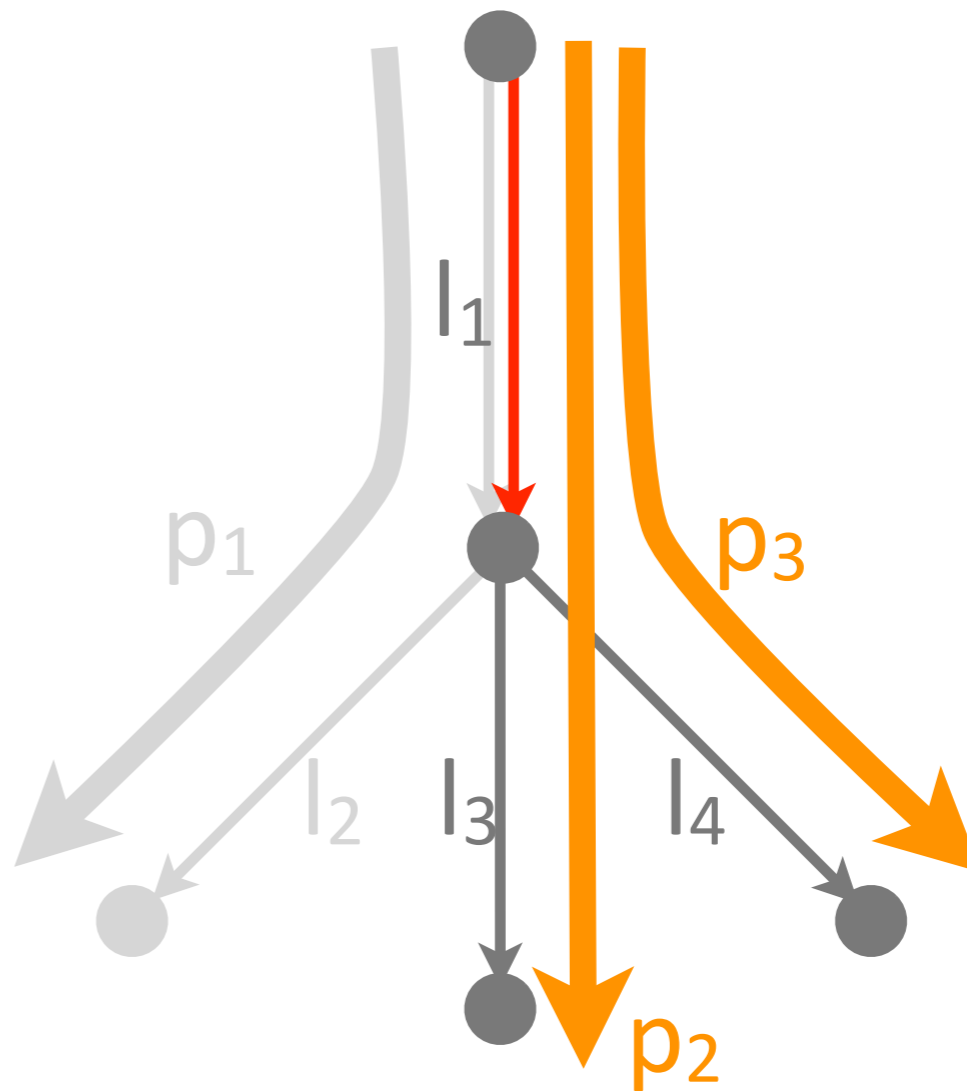
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$$Y_{23} = X_1 + X_3 + X_4$$



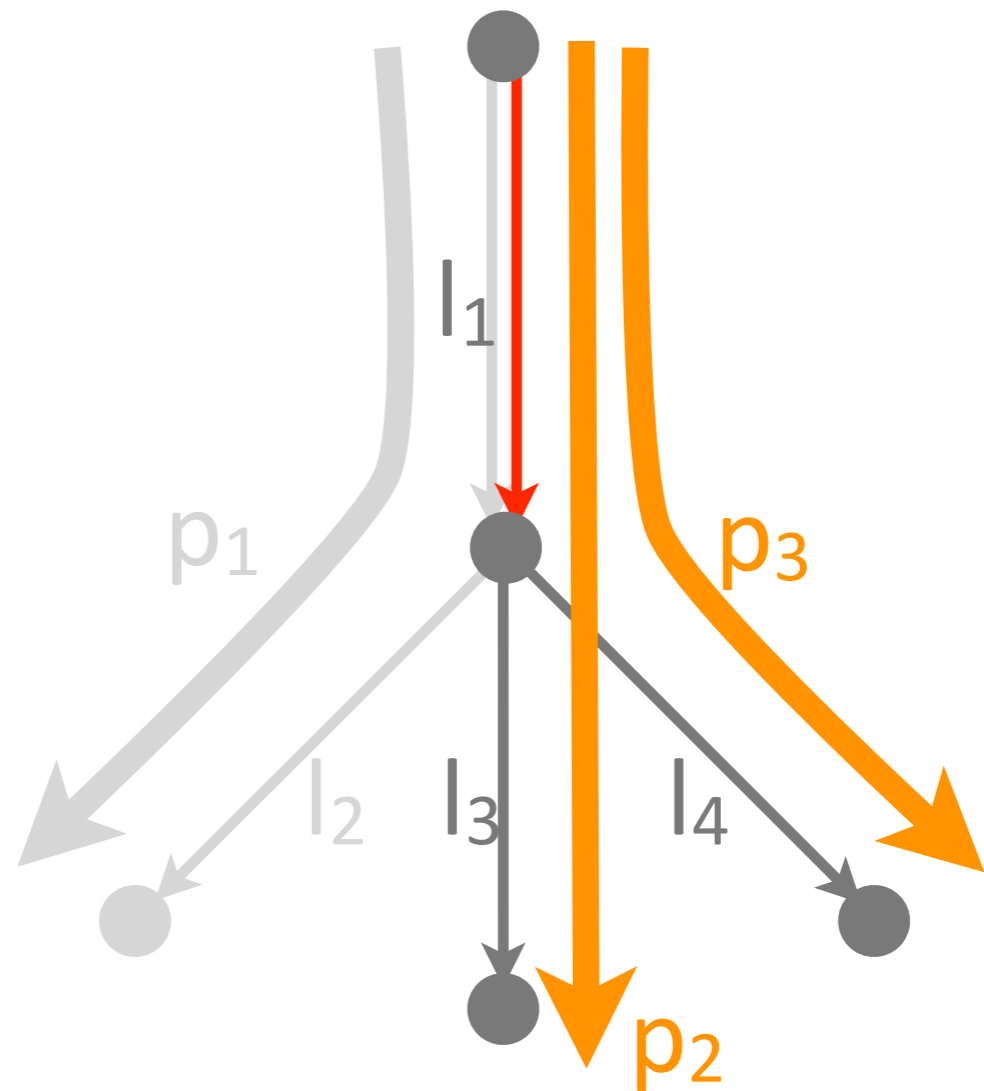
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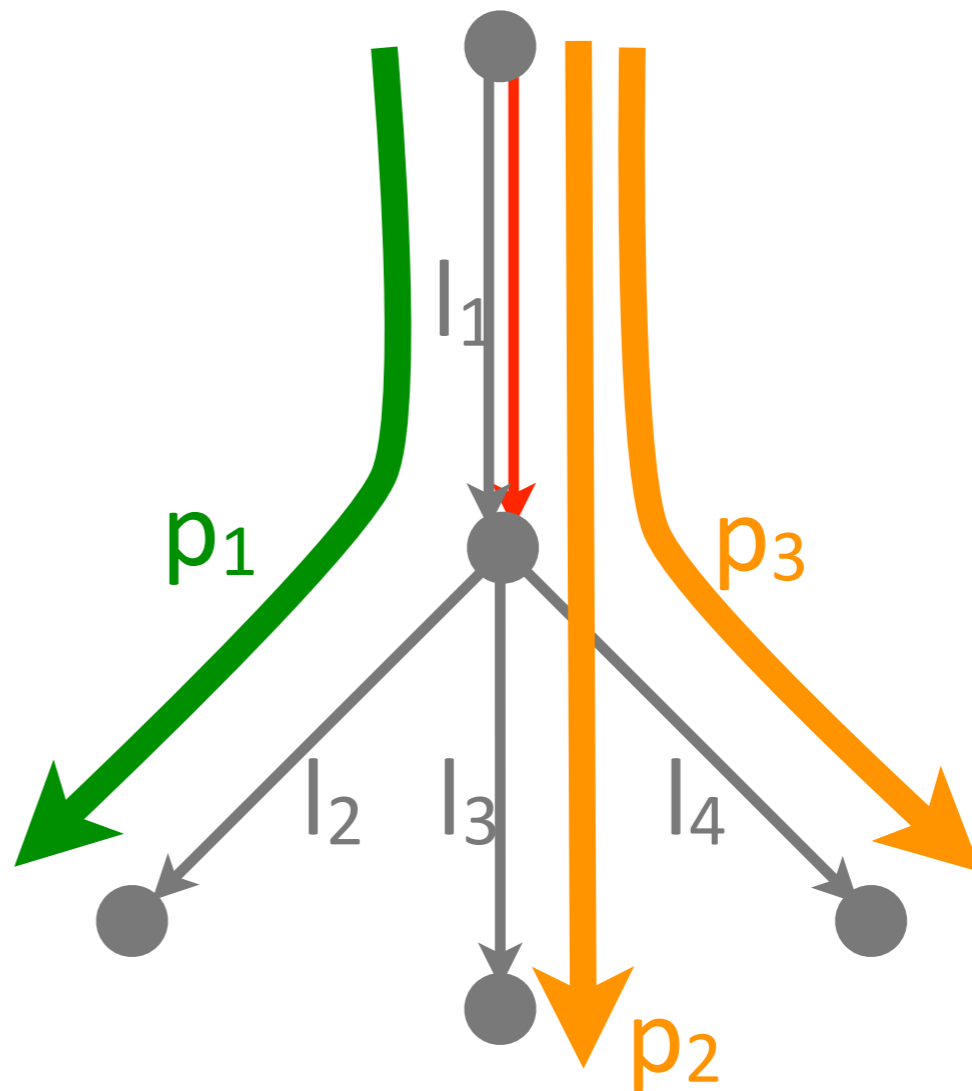
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Localizable violation

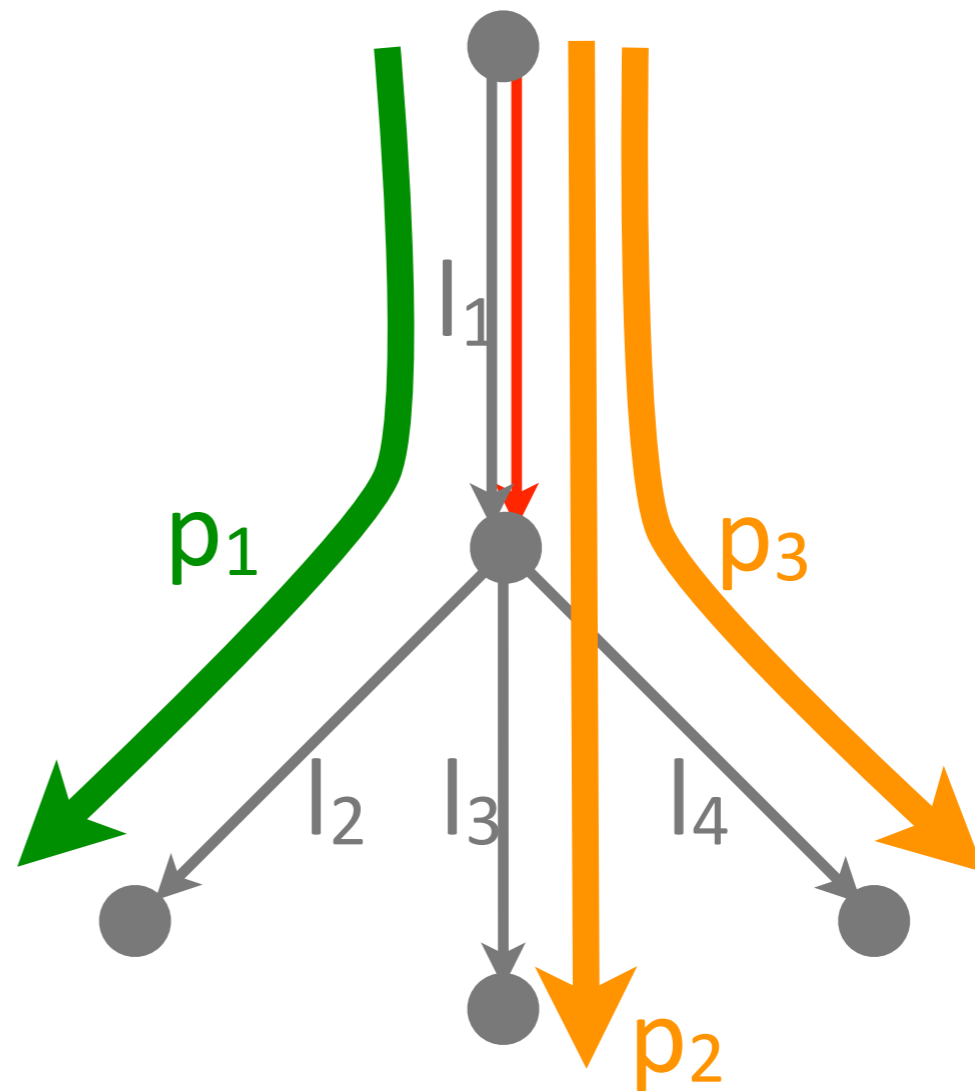
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$$Y_2 = X_1 + X_3$$

$$Y_3 = X_1 + X_4$$

$$Y_{23} = X_1 + X_3 + X_4$$



Localizability

- ▶ We can localize a neutrality violation to a particular link sequence, if there exist at least two path pairs that intersect exactly at this link sequence (...)

Outline

- ▶ Observability of neutrality violation
- ▶ Localization of neutrality violations
- ▶ **Algorithm + results**

Algorithm

- ▶ Considers each link sequence
- ▶ Identifies path pairs that intersect exactly at this link sequence
- ▶ Checks whether these form an unsolvable tomographic system of equations

Measurements

- ▶ Divide time into intervals
- ▶ Measure “congestion probabilities”
 - *count the intervals in which a path or a pair of paths is congestion-free*

Output

- ▶ Non-neutral link sequences
 - *include at least one non-neutral link*
 - *satisfy our localization condition*

Metrics

- ▶ False positives

- *fraction of neutral links that are in a link sequence that is misclassified as non-neutral*

- ▶ False negatives

- *fraction of non-neutral links that are not in a link sequence that is classified as non-neutral*

- ▶ Granularity

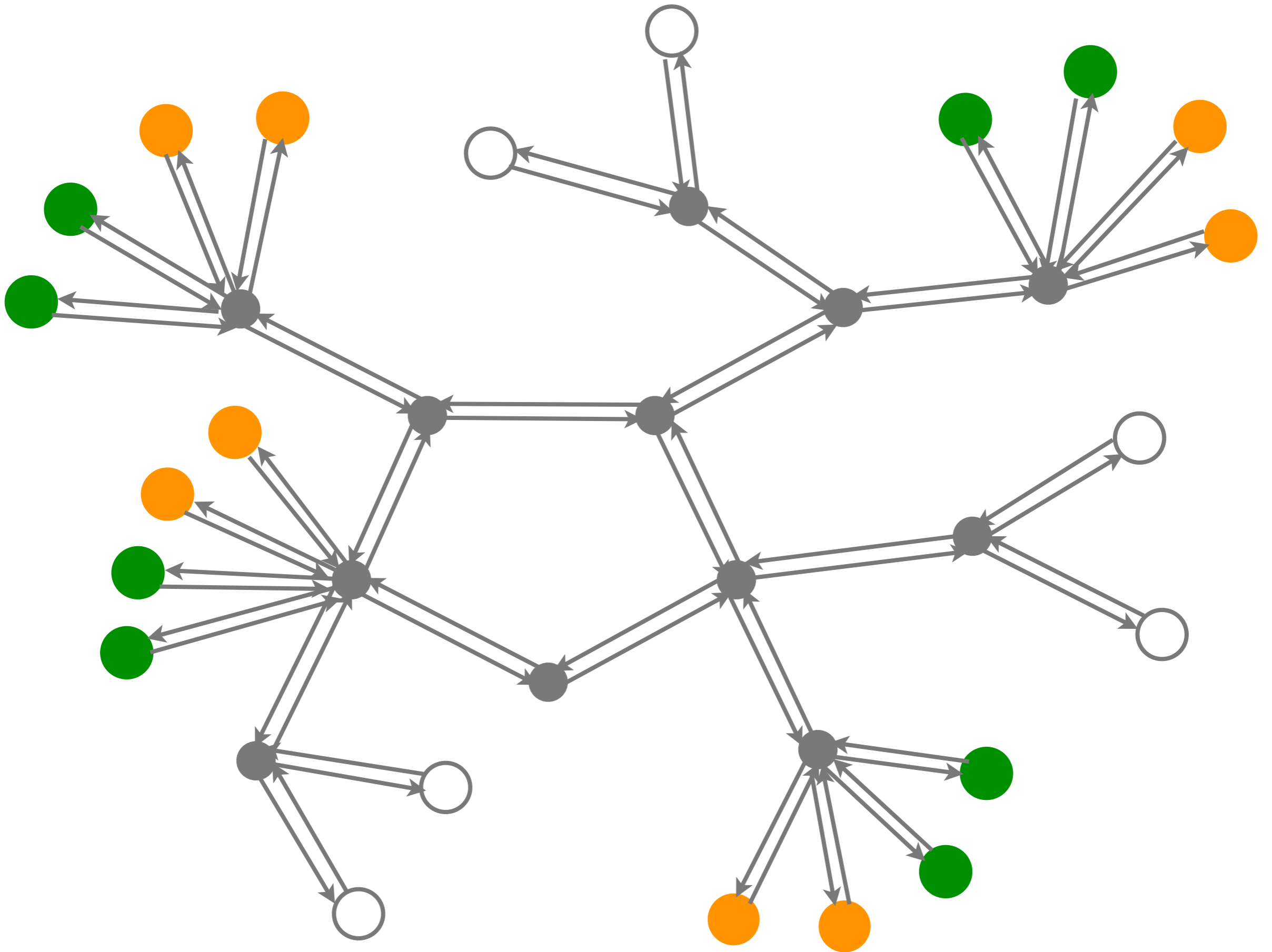
- *average size of link sequences classified as non-neutral*

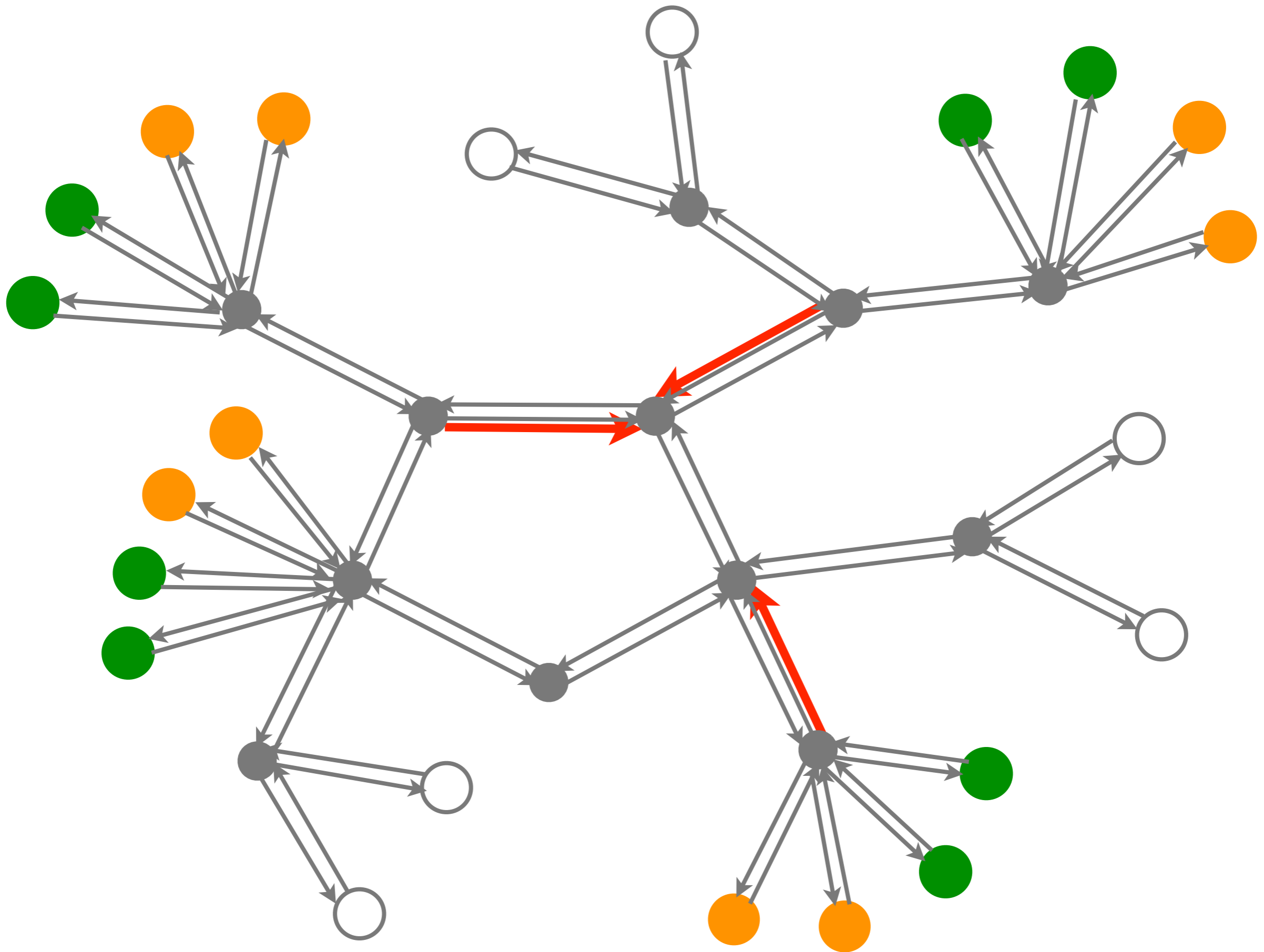
Evaluation platform

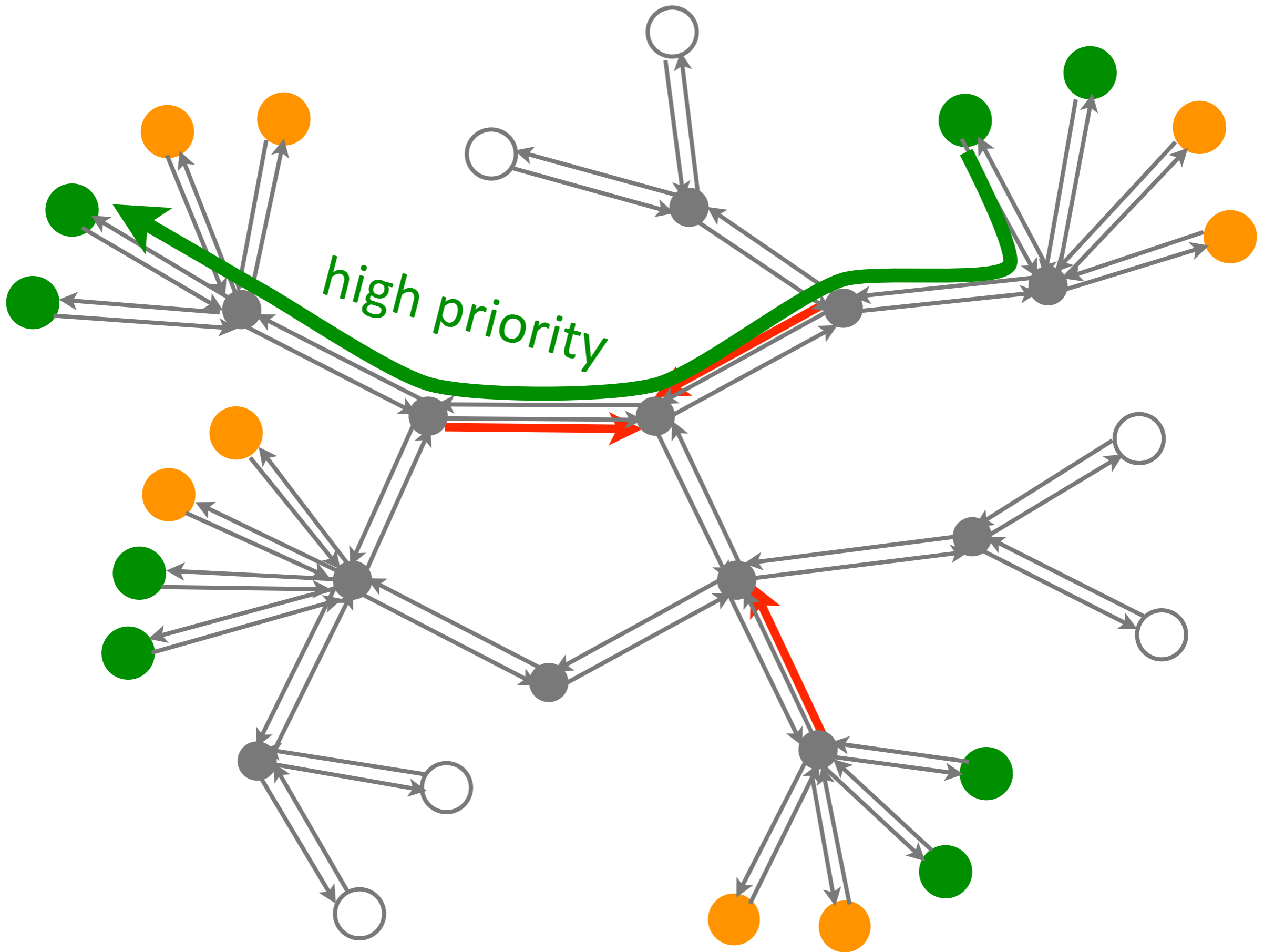
- ▶ Network emulator (LINE)
 - *virtual interface per end-host*
 - *runs in user space*
- ▶ Real network stacks, TCP traffic
- ▶ Real packet queues, policers, shapers
 - *(in software)*
- ▶ Simulated transfer and propagation delay

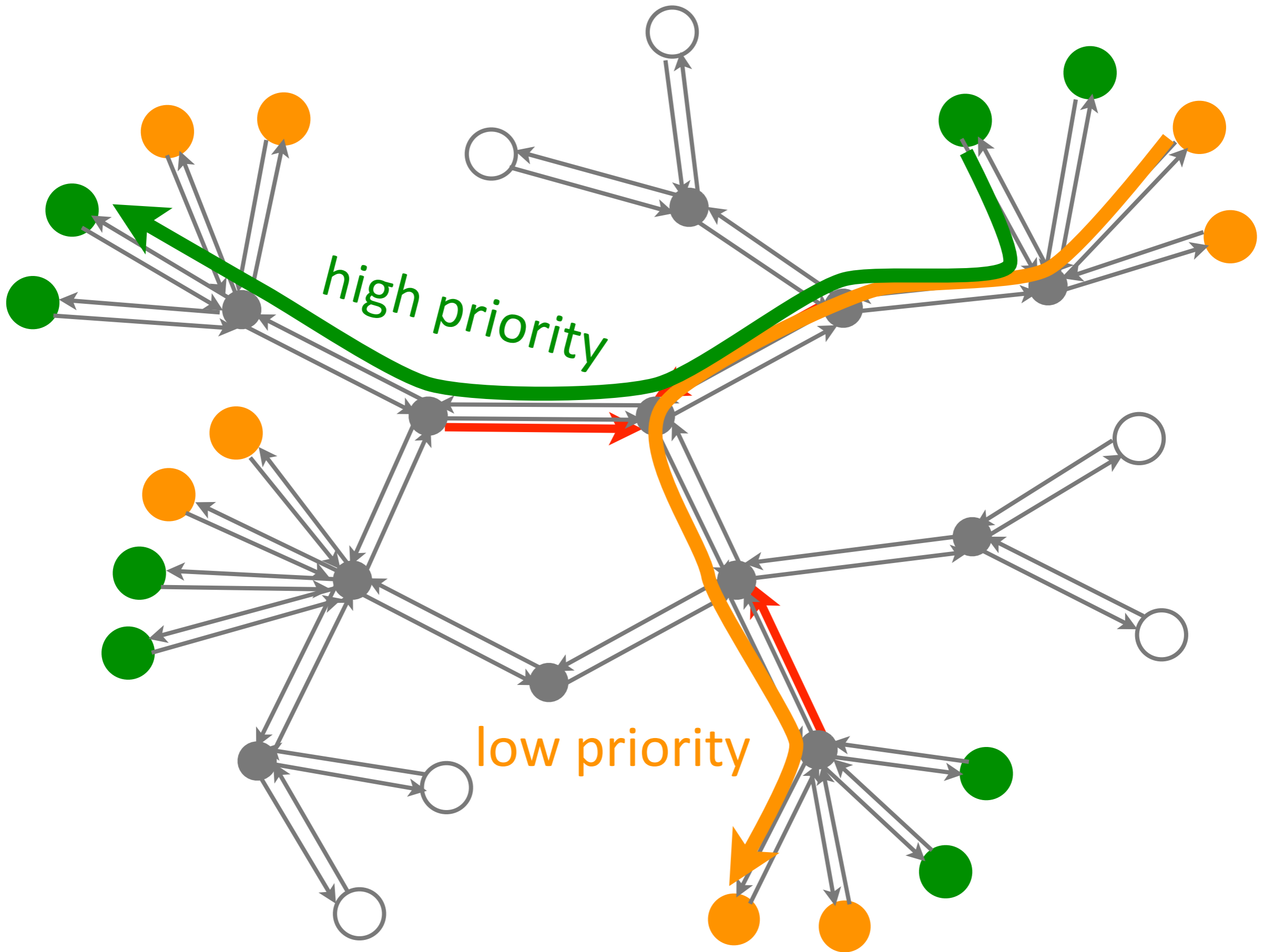
Simplest setup: uniform traffic

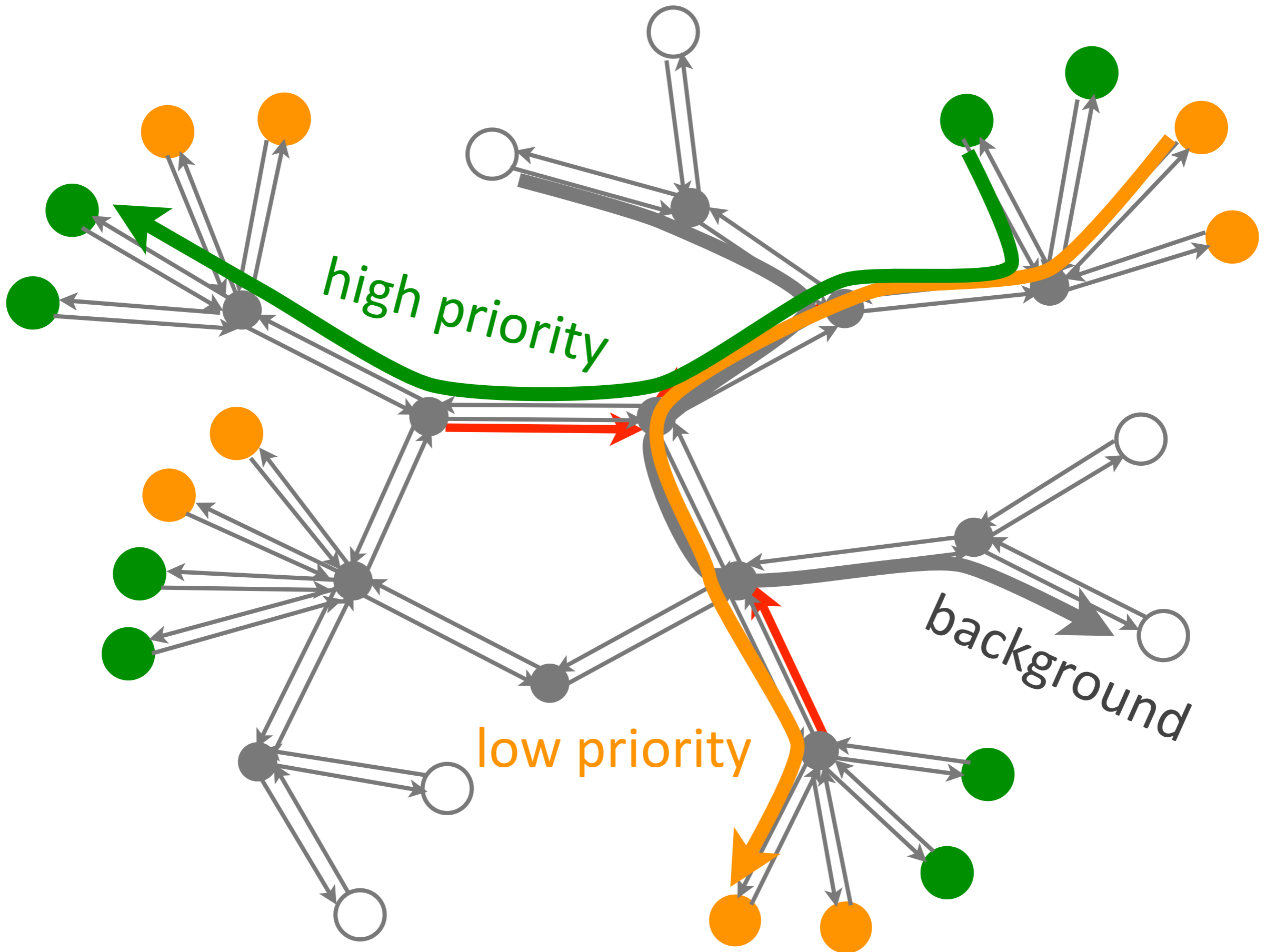
- ▶ Two traffic classes: high and low priority
- ▶ All traffic has the same TCP flow properties
- ▶ All links implement drop-tail policy
- ▶ Non-neutral links police low-priority at 30%







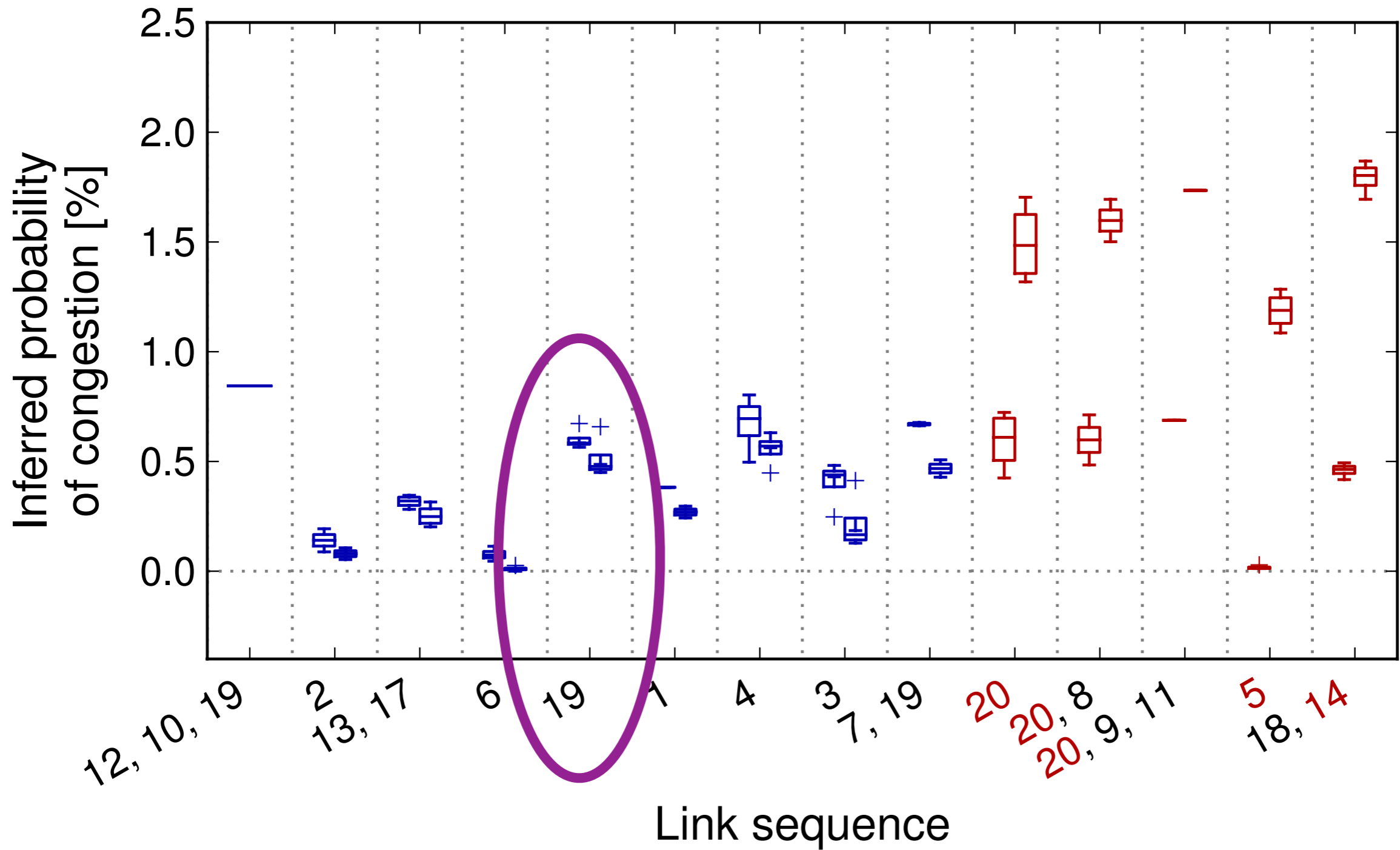


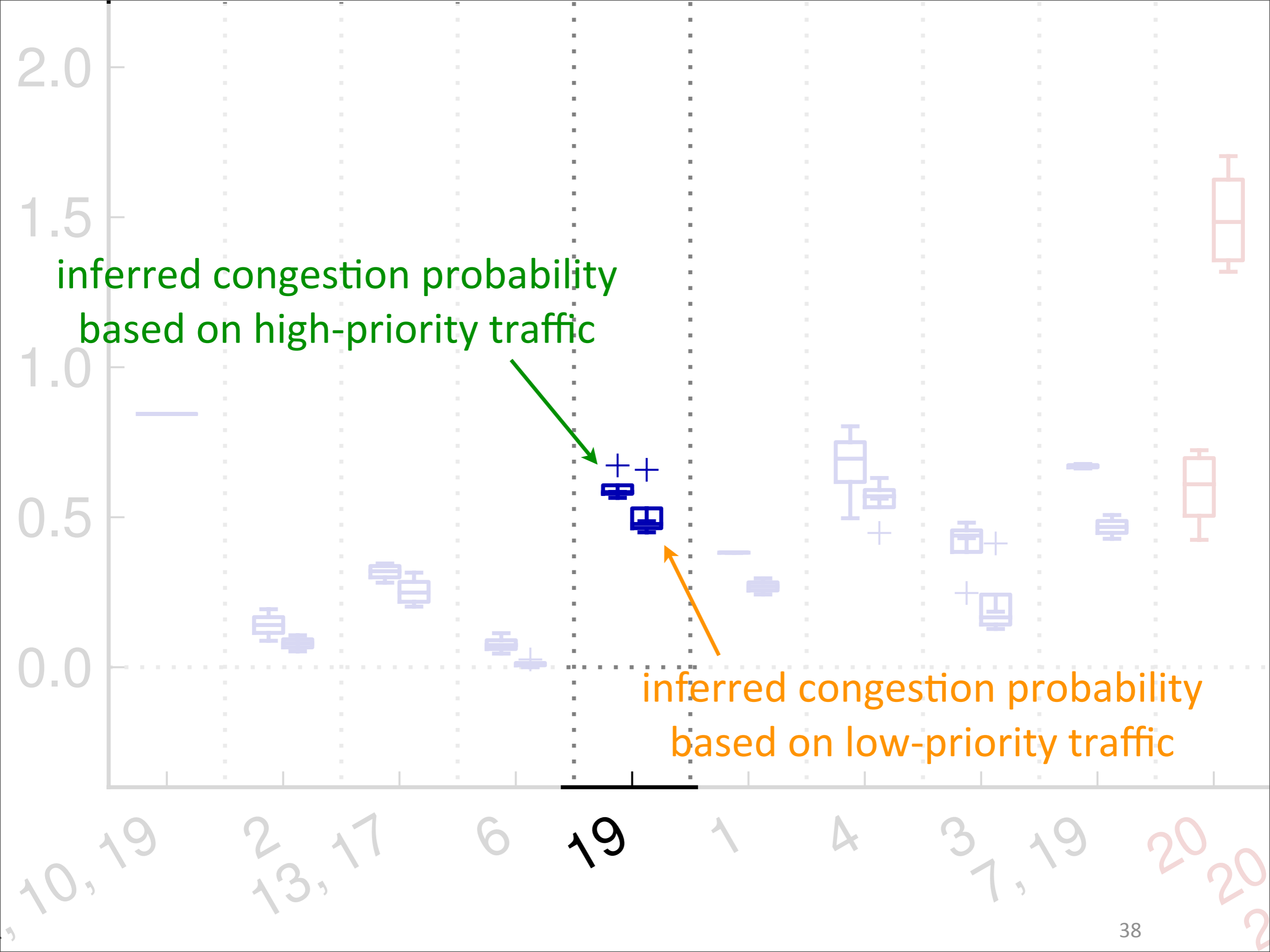


Results

- ▶ No false positives
- ▶ No false negatives
- ▶ Granularity: 1.8

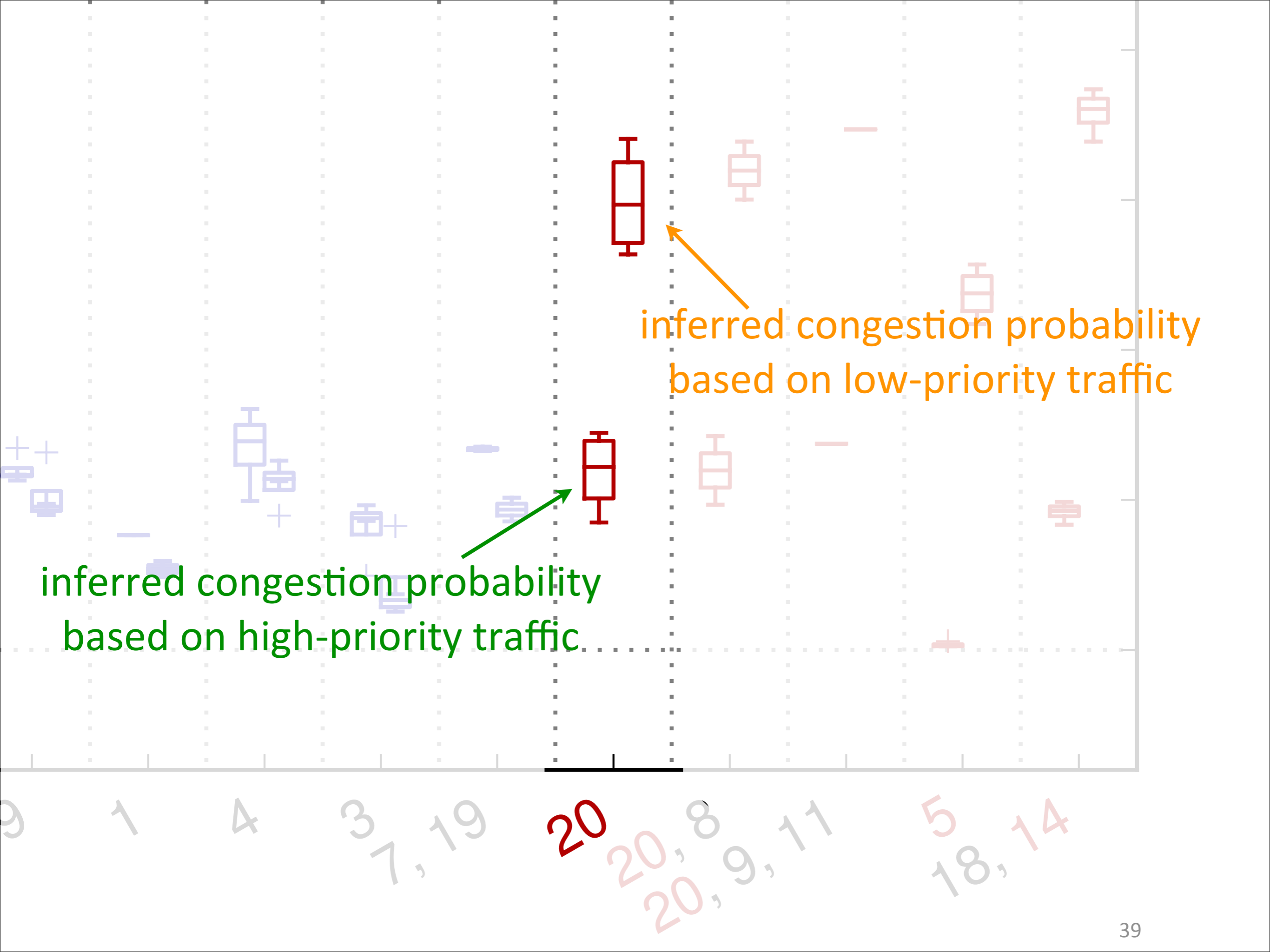
Under the hood





inferred congestion probability
based on high-priority traffic

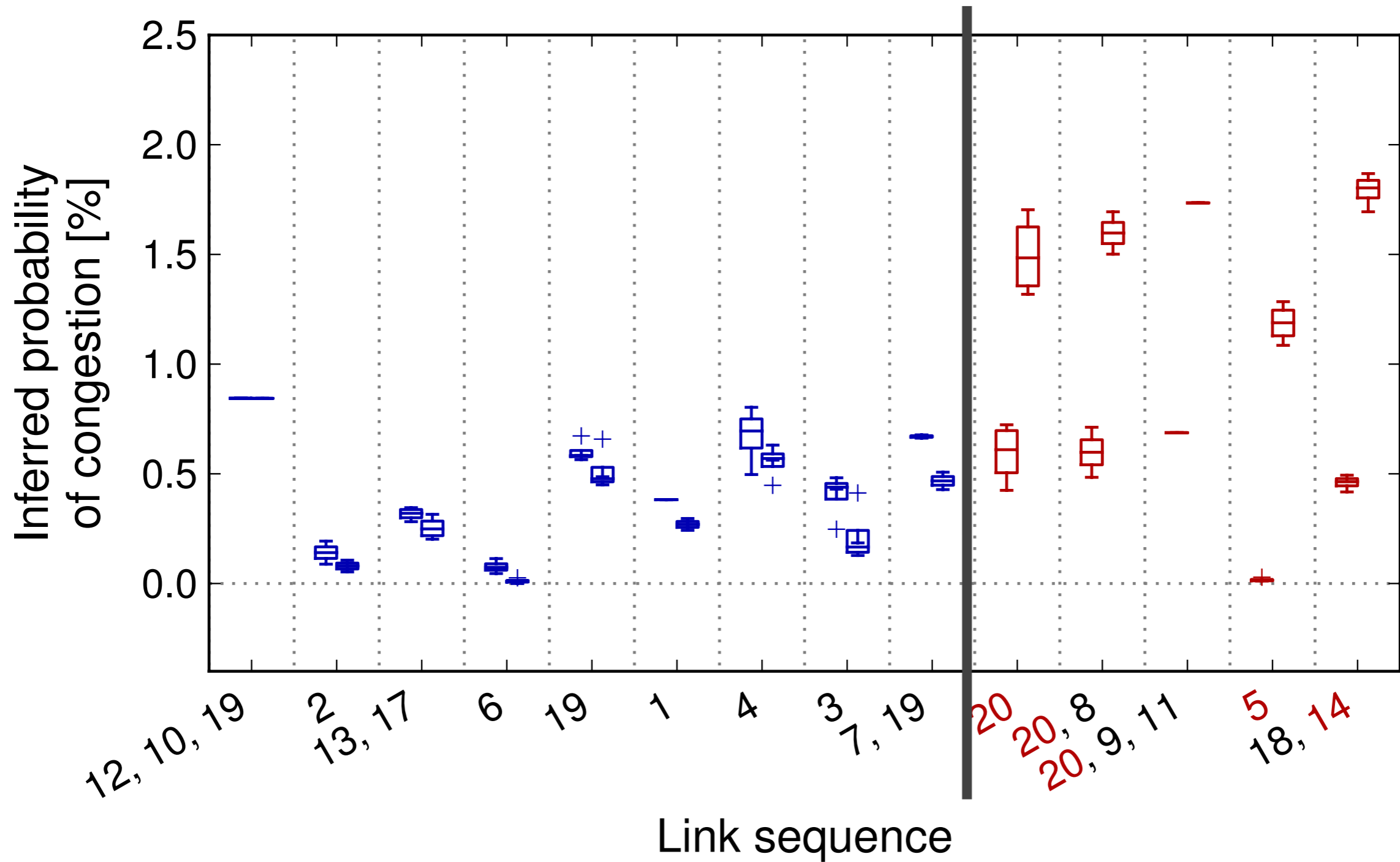
inferred congestion probability
based on low-priority traffic



inferred congestion probability based on high-priority traffic

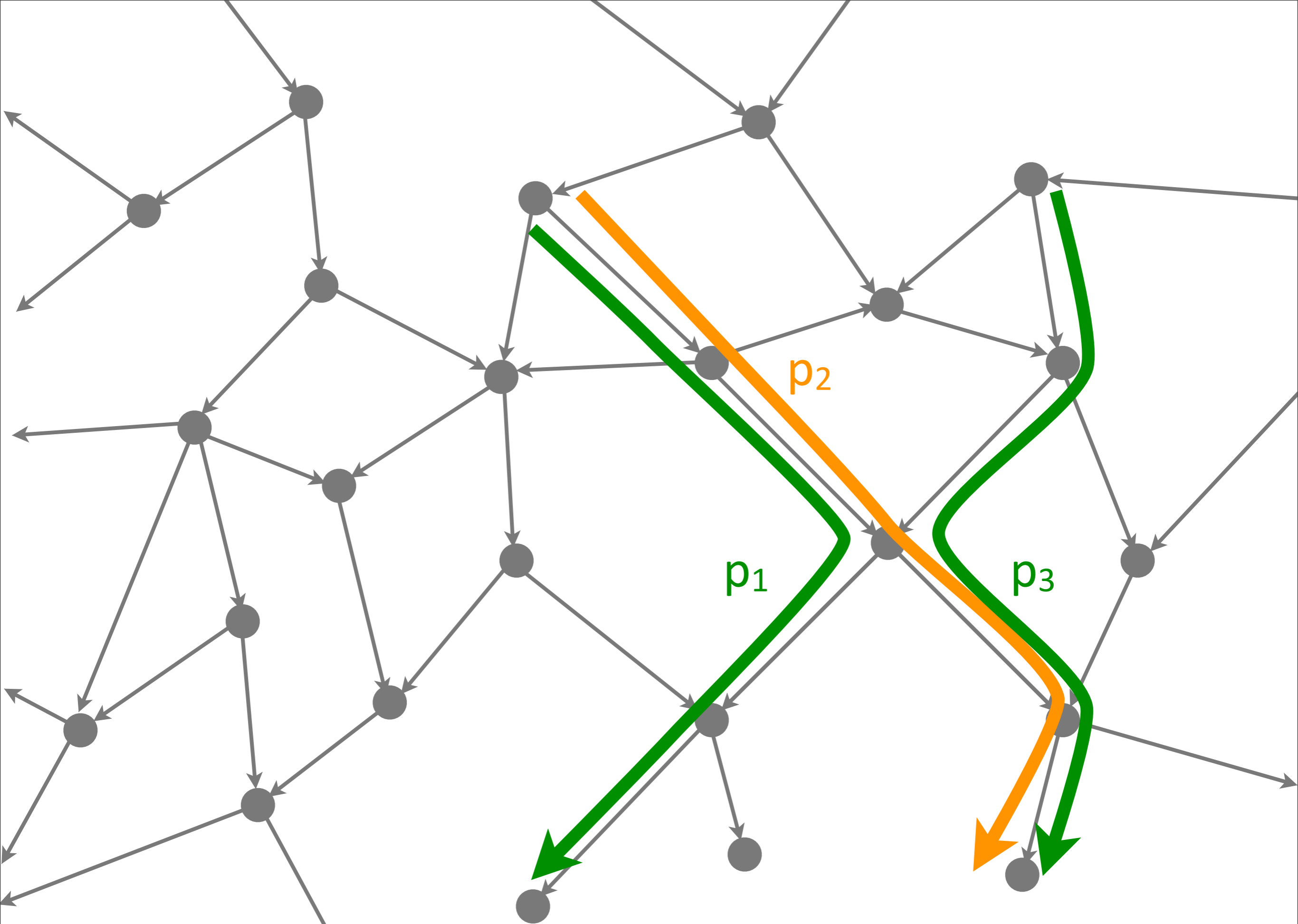
inferred congestion probability based on low-priority traffic

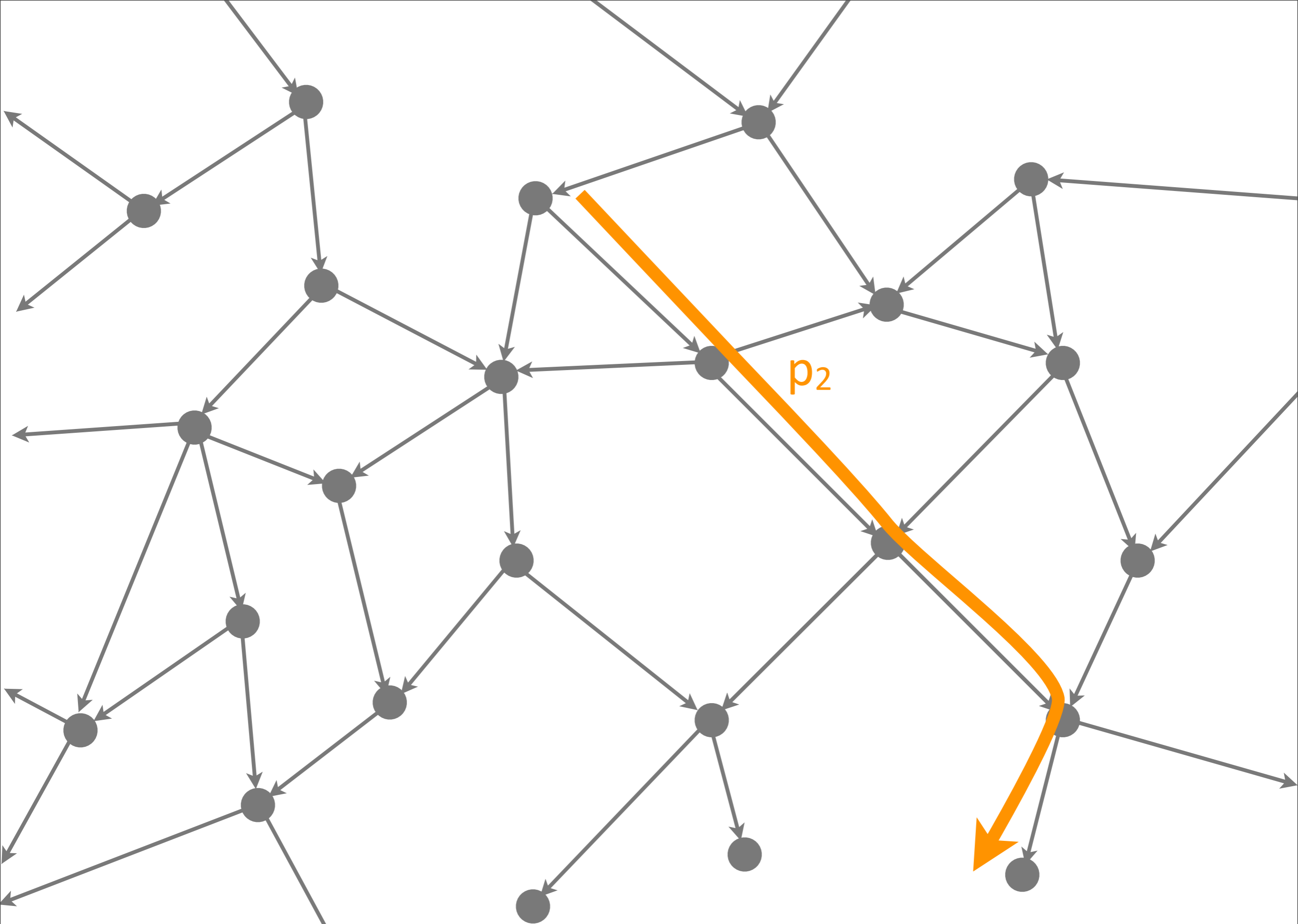
Under the hood



In the paper

- ▶ Theoretical assumptions
 - *link independence, class correlation*
- ▶ Solutions to practical problems
 - *TCP cautiousness, loss burstiness*
- ▶ Other experimental setups
 - *varying flow sizes, RTTs, congestion control algorithms, policing/shaping rates*





Related work

- ▶ Detection of **application**-layer and **transport**-layer differentiation
 - *DiffProbe, Kanuparth and Dovrolis, 2010*
 - *Glasnost, Dischinger et al., 2010*
- ▶ Detection of traffic shaping
 - *ShaperProbe, Kanuparth and Dovrolis, 2011*
 - *Packsen, Weinsberg et al., 2011*

Contributions

- ▶ **Detection** on neutrality violations independently from differentiation criteria
 - *iff there exists a **distinguishable virtual link** in the neutral equivalent*
- ▶ **Localization** of neutrality violations to specific link sequences
 - *if there exist two **path pairs** that intersect exactly at that link sequence (...)*