# Asynchronous Convergence of Policy-Rich Distributed Bellman-Ford Routing Protocols

SIGCOMM 2018

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New correctness results for general **policy-rich** distance-vector and path-vector protocols:

- A new proof technique which allows us to avoid directly reasoning about the asynchronous nature of the protocols.
- Using it we prove stronger and more general results than previous work.
- All results are fully formalised in the theorem-prover Agda and can be easily extended.

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Non-computer scientists: "Wow, that must be hard!"

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Computer scientists: "Why are you doing that? Isn't that solved?"

• Routing oscillations (i.e. non-convergence)



• Multiple final states (i.e. non-deterministic convergence)



We abstract the key features of a routing protocol into a routing algebra  $^1$ :

- A set of path weights
- A choice operator  $\oplus$  defined on weights
  - such that  $x \oplus y$  is either equal to x or is equal to y
- A set of policy functions F used to label edges
  - if you've configured a router think of an  $f \in F$  as a route map
- Some weak axioms for  $\oplus$  and F.

<sup>&</sup>lt;sup>1</sup>Inspired by Sobrinho 2005

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 $f(x\oplus y)=f(x)\oplus f(y)$ 



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## Example of violating distributivity

Shortest-paths with "no more than one blue edge".

- Path x has one blue edge in it
- Path y has no blue edges in it
- The edge A to B is blue
- Node B prefers route x, i.e.  $x \oplus y = x$



We will define a **policy-rich algebra** as one that allows us to violate distributivity.

Sobrinho 2005 showed there is a hierarchy of correctness conditions for path-vector protocols:

- Distributive algebras (long history of semirings)
- Strictly increasing algebras
- Networks with only algebraically free-cycles

The algebra is distributive iff:

$$\forall f, x, y : f(x \oplus y) = f(x) \oplus f(y)$$

i.e. everyone has a common preference order Advantages:

• Global optimum!

Disadvantages:

• Very restrictive as to the problems you can solve.

A network's cycles are free with respect to an algebra if going around a cycle is never an improvement.

Advantages:

• Least restrictive. Necessary for convergence.

Disadvantages:

- Conditions on the *topology* not just the algebra.
  - Requires global coordination to check!
- Verifying whether a network is cycle-free is NP-hard.

# Strictly increasing

An algebra is *strictly increasing* if extending a route makes it worse:

 $\forall f, x : x < f(x)$ 

where  $x \leq y \triangleq x \oplus y = x$ ,  $x < y \triangleq x \leq y$  and  $x \neq y$ .

Advantages:

- Property of the algebra, hence independent of the network.
- Much more expressive than distributive algebras.
- Conditional policies ("route maps") preserve this property.

Disadvantages:

- Local optimums instead of global optimums.
- Only a sufficient rather than a necessary condition.

If the algebra is strictly increasing then:

- Path-vector protocols converge to a unique solution.
- Distance-vector protocols with a finite set of weights converge to a unique solution.
  - even policy rich ones
- Doesn't require in-order reliable delivery.

Our proofs use new techniques.



This talk will not go into the details. If interested please read the paper!

All results formalised in the theorem proving language Agda. The library is freely-available and easily extendable.

- http://wiki.portal.chalmers.se/agda/pmwiki.php
- https://github.com/MatthewDaggitt/agda-routing

What are the problems with the *algebra* of BGP?

- 1. The MED attribute means that the  $\leq$  order is not transitive, which is nearly impossible to reason about.
- 2. Local preferences are erased so the algebra is not strictly increasing i.e. f(x) < x.

It may be impossible to use our results in inter-domain BGP but we hope our results may be applicable to intra-domain BGP applications such as data centres.

Beyond BGP we hope that the results will be used when designing new policy-rich distance-vector and path-vector protocols. We have defined a policy-rich shortest paths algebra, inspired by BGP.

Routes can be tagged with community values and these can be used by policies to make decisions.

Unlike BGP the local preferences are never erased.

This has been defined in Agda and proved correct.

It can easily implement the "no more than two blue links" example.

- Can we incorporate checks for strict increasingness into automatic policy generation tools?
  - e.g. Propane (Beckett et al. SIGCOMM 2016)
- Is it possible to have hidden information in a strictly increasing algebras without global coordination?
- What's the rate of convergence of strictly increasing algebras?
  - Partial answer in our upcoming ICNP paper.

Routes are defined as follows:

data Route : Set where invalid : Route valid : LocalPref  $\rightarrow$  CommunitySet  $\rightarrow$  SimplePath  $n \rightarrow$  Route

### Agda example: choice

The choice operator  $\oplus$  is defined as follows:

```
\oplus : Route \rightarrow Route \rightarrow Route
invalid \oplus s = s
r \oplus invalid = r
r@(valid | cs p) \oplus s@(valid k ds q) with <-cmp | k
\dots | tri < l < k = r
\dots | tri> k < l = s
... | tri\approx l=k with <-cmp (length p) (length q)
\dots | tri< |p| < |q| = r
... | tri> |p| > |q| = s
... | tri \approx |p| = |q| with p \le \text{lex}? q
... | yes p < q = r
... | no p \not< q = s
```

data Policy : Set<sub>1</sub> where reject : Policy addComm : Community  $\rightarrow$  Policy delComm : Community  $\rightarrow$  Policy compose : Policy  $\rightarrow$  Policy condition : Condition  $\rightarrow$  Policy  $\rightarrow$  Policy incrPrefBy :  $\mathbb{N} \rightarrow$  Policy

$$\begin{array}{ll} f: (\mathsf{Node} \times \mathsf{Node} \times \mathsf{Policy}) \to \mathsf{Route} \to \mathsf{Route} \\ f \_ & \mathsf{invalid} &= \mathsf{invalid} \\ f(i, j, \mathit{policy}) (\mathsf{valid} \ \mathit{l} \ \mathit{cs} \ \mathit{p}) \ \mathsf{with} \ i \notin ? \ \mathit{p} \\ \dots \ | \ \mathsf{no} \ i \in \mathit{p} = \mathsf{invalid} \\ \dots \ | \ \mathsf{yes} \ i \notin \mathit{p} &= \mathsf{apply} \ \mathit{policy} \ (\mathsf{valid} \ \mathit{l} \ \mathit{cs} \ ((i, j) :: \mathit{p} \ | \ i \notin \mathit{p})) \end{array}$$